



**Description****BACKGROUND OF THE INVENTION**

The invention relates to a system of spacecrafts according to the preamble of claim 1.

The spacecraft of this type is described in JP-A-56-99899, JP-A-61-268599 and JP-A-2-24073, and "Study of Near-by Working System in Space" in the 31st joint lecture meeting of space science and technology, 3G2.

A single spacecraft, as mentioned in the documents, is physically divided into two sections, or a moving portion and a portion to be at rest, which are to achieve their objects with ease.

TRANSACTIONS OF THE AMERICAN SOCIETY OF MECHANIC ENGINEERS, JOURNAL OF ENGINEERING INDUSTRY, vol. 107, no. 1, February 19, 1985, NEW YORK (US), pages 49-54, R. FRENCH ET AL. "SATELLITE SERVICING BY TELEOPERATORS" discloses a teleoperator manouvering system (TMS) which may be a shuttle-launched, ground-based satellite servicing vehicle or one based at a space station, controlled by man-in-the-loop. It serves to assist the assembly and placement of various space station elements as well as to provide logistics module transportation from the shuttle to the space station. The TMS includes communication means for communication for example with ground stations.

It is an object of the invention to provide a spacecraft system having a plurality of spacecrafts whereby the spacecrafts can operate independent of each other and which also can cooperate with each other such that the spacecraft system is capable of carrying out various types of missions.

This object is achieved by a system of spacecraft according to claim 1.

The spacecraft system according to the invention is capable of reclaiming old spacecrafts which closed their lives to thereby maintain the space environment satisfactory.

The spacecraft system according to the invention is capable of carrying out a mission by detaching components from a useless spacecraft and combining the components with others.

The spacecraft system according to the invention is capable of building a large system comprising spacecrafts each of which acts as an independently operated function.

One of the feature of the present invention is that each of the spacecrafts has at least a communication apparatus and a mission having at least one operation function. In addition, mission objects are floated in outer space together with the spacecrafts and are combined by the mission. Moreover, a central control station controls the spacecrafts and mission to operate through the communication apparatus.

The spacecraft also includes a propulsion apparatus for driving the space craft itself.

The spacecrafts which communicate with the central control station through the communication apparatus, can also communicate through a space repeater with the central control station.

The central control station can be installed in space, on the earth and other planets.

The mission is divided into a plurality of units for respective independently operated functions so as to be separable from the spacecrafts, and stored in a system dock. The plurality of units include, for example, an orbital working means, a communication unit, a posture control unit, a propulsion unit and a data processing unit.

The mission may also mean a group of units for making up a complete space facility.

Of these units, the orbital working means, also referred to as orbital space worker, has a manipulator and includes at least a communication portion, a propulsion portion for driving the worker itself, and a driver for driving the manipulator.

The mission objects may include a solar power generator having a photosensitive portion for receiving solar energy, a power transmitting portion for transmitting the converted electric power from the photosensitive portion to the ground, and a structure for mounting the photosensitive portion and the power transmitting portion, and the structure, apparatus and materials to be used in a space station, and so on. The mission objects may also include the orbital space workers, communication units, posture control units, propulsion units and data processing units separated from the spacecrafts each of which has a plurality of units and is housed in the system dock. Furthermore, the mission objects may include the old spacecrafts which closed their lives.

The central control station may be a ground control station or a space control station.

The orbital space worker may be used to combine at least the communication unit, the posture control unit, the propulsion unit and the data processing unit separated from a spacecraft in accordance with commands from the central control station and the spacecrafts. In addition, the orbital space worker may be used to combine any one of at least the communication unit, the posture control unit, the propulsion unit and the data processing unit, with the solar power generator, structure, apparatus, materials and so on.

Furthermore, the orbital space worker is used to assemble a mission object in accordance with a command from a spacecraft in which this worker is housed, and in cooperation with other orbital space workers of spacecrafts.

Thus, a plurality of spacecrafts perform their own missions, so that a space station, a communication satellite, a supervisory satellite and so on can be rationally assembled. In addition, the old communication satellites which closed their lives are recovered and reclaimed by removing or exchanging parts so that the useless floating residues can be removed from outer space and that the space environment can be kept clean or satisfactory.

## BRIEF DESCRIPTION OF THE DRAWINGS

Fig. 1 is a block diagram of the principle of the dispersion-type spacecraft system of the invention;  
 Fig. 2 is a block diagram of the conventional division-type spacecraft system;  
 Fig. 3 is a table showing the comparison between the dispersion-type spacecraft system and the division-type spacecraft system;  
 Fig. 4 shows one example of the solar power satellite;  
 Fig. 5A is a plan view of another example of the solar power satellite;  
 Fig. 5B is a magnified detailed diagram of the portion surrounded by a circle in Fig. 5A;  
 Fig. 6 is a side view of the structure unit;  
 Fig. 7 is a plan view of a power generation unit shown in Fig. 6;  
 Fig. 8 shows major components of the solar power satellite based on the virtually connected spacecraft system;  
 Fig. 9 is a block diagram of the construction of the orbital space worker;  
 Fig. 10 is a perspective view of the orbital space worker in space;  
 Fig. 11 is a perspective view of a plurality of orbital space workers in space;  
 Fig. 12 shows the construction of the orbital space worker based on the transform spacecraft system;  
 Fig. 13 shows the construction of the orbital space worker assembled by a combination of units;  
 Figs. 14A, 14B and 14C are perspective views of examples of the orbital space worker assembled by a combination of the units shown in Fig. 13;  
 Fig. 15 shows another construction of the orbital space worker based on the transform spacecraft system;  
 Fig. 16 is a perspective view of the orbital space worker of the construction shown in Fig. 15;  
 Fig. 17 shows the experiment of the transform spacecraft system;  
 Fig. 18 is a perspective view of the orbital space worker to be used for the experiment of the virtually connected spacecraft system;  
 Fig. 19 shows the test of the virtually connected spacecraft system;  
 Fig. 20 is a perspective view showing an example of the transport of the structure unit by the cooperation of the management/control portion and operation executing portion of the orbital space worker;  
 Fig. 21 is a perspective view of an example of the transport of a flexible structure;  
 Fig. 22 shows the experiment of mounting the flexible structure on the structure unit;  
 Fig. 23 shows the structure of major units of the unmanned space laboratory base;  
 Fig. 24A is a perspective view of the unmanned space laboratory base;

Fig. 24B is a perspective view of an example of the orbital space worker;  
 Fig. 25 is a perspective view of one example of the construction of the unmanned space laboratory base;  
 Fig. 26 shows the recovery of waste products from the unmanned space laboratory base;

## DESCRIPTION OF THE PREFERRED EMBODIMENTS

Embodiments of the invention will be described with reference to the accompanying drawings. Fig. 1 shows an embodiment of the spacecraft system of the invention.  
 Referring to Fig. 1, there are shown dispersion-type space crafts 1a, 1b and 1c which have missions 1, 2 and 3, respectively. The mission means 1, 2 and 3 mean a group of units for making up a complete space facility. The space crafts 1a, 1b and 1c also have communication controllers 2a, 2b and 2c, respectively. Fig. 2 shows a conventional division-type spacecraft 3. The spacecraft 3 has a central processor 3a and mission blocks 3b, 3c and 3d. The mission blocks 3b, 3c and 3d have missions 1, 2 and 3, respectively. The dispersion-type space crafts 1a, 1b and 1c shown in Fig. 1 communicate with each other or with a ground control station or space control station not shown. In other words, the space crafts 1a, 1b and 1c are independent of each other, and carry out their missions 1, 2, 3, respectively. On the other hand, the conventional division-type spacecraft 3 is a single unit, and thus a plurality of missions 1, 2 and 3 are not independent of each other, but are sequentially performed one by one. Fig. 3 is a diagram showing the comparison of the dispersion-type space crafts 1a, 1b and 1c with the division-type spacecraft 3. The division-type spacecraft 3 is excellent in its working property, but poor in the extensibility, or unfoldability, maintainability, continuity of operation and realization expectancy.

The extensibility means a possibility for building up spacecraft systems extensively. In the dispersion-type space crafts, a spacecraft is launched and combined with a conventional spacecraft to carry out a new mission. In the division-type space crafts, a new mission cannot be carried out with a combination. In relation to the maintainability, the dispersion-type has a good feature since the components can be changed in comparison with the division-type. In the continuity of the operation, the dispersion-type has a better feature as well.

In the case that the dispersion-type spacecraft is operated practically, since the space crafts are independently operable, it is sufficiently operable to transmit operation commands to the space crafts individually. In the case that it is insufficient to operate independently, the spacecraft is manually operated, so the operation to the spacecraft is complicated.

Accordingly, in case of building up a large structure, for example, a solar power satellite, it is possible to build up the satellite step by step with use of the dispersion-

type spacecraft, so that the structural work can be built from a small to large scale.

The dispersion-type spacecrafats 1a, 1b and 1c lack easiness in operation, but satisfy the other requirements. In addition, the dispersion-type spacecrafats are able to most probably realize the operation for parts of the missions. A solar power satellite as an example of this realization will be described below.

Fig. 4 shows a conventional division-type solar power satellite 11. Referring to Fig. 4, there are shown a solar cell array 40, a power transmission antenna 50, a ground power receiving antenna, and the earth 7, each of these are divided. The solar cell array 4 has an attitude controller 4a mounted thereon to control the attitude of the antenna so that the antenna most effectively receive the rays of the sun. The solar cell array 40 and the power transmission antenna 5 are connected by a super conductive power-collecting circuit network 4b so that the electric power can be transmitted to the power transmission antenna 50. The power transmission antenna 50 has the attitude controller 4a and a refrigerator 4c mounted thereon. A microwave is transmitted from the power transmission antenna 50 to the ground power receiving antenna 6.

In the solar power satellite shown in Fig. 4, since the solar power satellite was proposed by Dr. Graser, many researchers have been investigated for a power transmission system from various different angles. The invention has specifically examined the construction of the solar power satellite.

The construction and maintenance of the solar power satellite are one of the major technical problems. Since it is difficult to launch the apparatus assembled on the earth, and then place it in orbit, the materials are launched and then assembled. However, the working of the spaceman in space away from the spaceship is dangerous, costly and time-consuming and thus it is considerably difficult. Thus, in place of the spaceman, an unmanned spacecraft can be considered to be developed for the space action. In other words, the units each of which constitutes the solar power satellite are acted as the spacecrafats, and are ordered to connect to each other. In addition, in place of the man, an orbital space worker performs a combination of the units constituting the solar power satellite. The development of the basic technology of the construction of the solar power satellite will be described with reference to Figs. 5 to 8.

Fig. 5A shows example of the solar power satellite 11 in the present invention in contrast to the conventional type shown in Fig. 4. The materials for constructing the solar power satellite 11 are launched into outer space and assembled independently in orbit as illustrated. The operation of assembling the solar power satellite 11 in orbit will be mentioned later. As shown in Fig. 5A, the solar cell array 4 in the present invention and the power transmission antenna 5 are each of a rectangular shape. Fig. 5B shows a magnified view of the portion surrounded by a circle. As shown in Fig. 5B, the solar cell array 4 is formed of a plurality of power generation units

9, and these power generation units 9 are supported by a structure unit 8. Also, the structure unit 8 has power control units 13 mounted thereon. These power control units 13 control the levels of the power generated from the power generation units 9. Moreover, command portions 12 are mounted on the structure unit so as to monitor the power generation units 9 and to monitor the angle of the solar cell array 4 to the sun light, thereby making the cells effectively receive the ray from the sun. The power transmission antenna 5 is formed of a plurality of power transmission antenna units 10. These power transmission antenna units 10 are supported by the structure unit 8. Although not shown in Figs. 5A and 5B, communication units are also mounted thereon so as to receive commands from the spacecrafats 1a, 1b and 1c described with reference to Fig. 1. Fig. 6 is a side view of the details of the solar cell array 4, the power transmission antenna 5 and the structure unit 8 shown in Figs. 5A and 5B. The structure unit 8 has power generation unit connectors 9a mounted through which the power generation units 9 can be mounted on the structure unit 8. Thus, the power generation units 9 can be easily mounted on the structure unit 8 in orbit. The structure unit 8 has a docking module 8a mounted at one end so as to be connected to the other structure unit 8. In addition, the structure unit 8 has thrusters 8b mounted at both ends in order to move. Furthermore, a core vehicle 8c is mounted on one end of the structure unit. The structure shown in Fig. 6 is one operation unit of solar cell array 4. The single core vehicle 8c is mounted on each operation unit. These operation units of solar cell array 4 are mostly assembled into a plurality of solar cell arrays 4. Fig. 7 is a plan view of the power generation unit showing one operation unit of solar cell array 4. The power generation unit 9 is formed of a plurality of solar arrays 9b. The structure unit 8 shown in Figs. 6, and the thruster 8b, core vehicle 8c and docking modules 8a which are mounted thereon, constitute one spacecraft. In other words, the structure unit 8 constitutes an independent spacecraft, or a dispersion-type spacecraft.

Fig. 8 shows the materials and apparatus which are necessary to form the solar power satellite 11 mentioned above. In other words, it includes the apparatus of command unit 12, power generation unit 9, power transmission antenna unit 10, structure unit 8, power control unit 13, orbital space worker 14, material storehouse 15, and propellant depot 16. Of these apparatus, the structure unit 8 and power generation unit 9 are already described with reference to Figs. 6 and 7. The other apparatus or units each have a communication section and a drive section and act as independent spacecrafats each having independently operated function. Thus, the power transmission antenna 10, command unit and power control unit 13 of the solar cell array 4 and power transmission antenna 5 shown in Figs. 5A and 5B respectively act as independent spacecrafats, or dispersion-type spacecrafats like the structure unit 8 and the power generation unit 9. These units are together or individually launched from

the ground into outer space, and thrown into orbit from the mother spaceship, as required.

Of the units necessary for assembling the solar power satellite 11, the command unit 12 receives commands from the mother spaceship, ground control station or space control station, and orders one operation unit of the solar power satellite 11 to be connected to other operation units by driving the thruster 8b. The plurality of units shown in Fig. 8 are major units. If these units are assumed to be a system dock, the system dock is formed of about 200 units. Therefore, the solar power satellite 11 is constructed by units of the system dock. The respective units of one system dock have a command leader not shown. The command leaders of the units are ordered to connect to each other by the command unit 12. The orbital space worker 14 of the units as described later is provided for each 10 system docks, for example. One or a plurality of orbital space workers 14 work together. The material storehouse 15 stores materials necessary for the solar generation satellite 11, and the propellant depot 16 stores fuel for propulsion. The system docks are housed in the mother spaceship.

The orbital space worker 14 will be described below. Each of the units constituting the solar power satellite 11 acts as one spacecraft. Each spacecraft makes rendezvous and docking on the basis of the command from the command unit 12. The orbital space worker 14 performs high-grade operations in place of the man. That is, the orbital space worker 14 executes the construction and maintenance operations, and responds to the commands from the ground control station or space control station to freely move in orbit.

Fig. 9 shows one example of the orbital space worker 14. The orbital space worker 14 is formed of an operation executing portion 21 and a management/control portion 22. The operation executing section 21 and the management/control section 22 have docking ports 100 and 110, respectively. When housed in the mother spaceship, the docking ports 100 and 110 are connected to each other. When the orbital space worker 14 is thrown into orbit from the mother spaceship, both the portions are separated as a result of the disconnection of the docking ports 100 and 110 as shown in Fig. 9. Since the orbital space worker 14 is one unit within the system dock, it has at least the command leader which receives the command from the command unit 12, and has the same function as the command unit in order to receive the commands from the ground control station or space control station. The management/control section 22 corresponds to this command unit. The management/control section 22 has an antenna 24 for receiving the commands from the ground control station or space control station, a long range communication portion 115 for amplifying the command to a certain level, a data processor 112 for discriminating the signals from the long range communication portion 115, a short range communication portion 111 and antenna 24 for transmitting the processed signal to the operation executing portion 21, a high performance computer 113, a large-capacity

battery 117, a power section 114 for charging the power from a solar battery paddle 119 to the large-capacity battery 117, and a fuel tank 116. The fuel tank 116 is used to supply fuel to and drive the docking port 110 and the other docking port 118 when the management/control section 22 is connected to another unit. Also, the management/control section 22 has the thruster 8b mounted as do the other units. The operation executing portion 21 has the antenna 24 for receiving the command from the management/control section 22, a transponder 101 for relaying the received command, a command decoder 102 for decoding the command from the transponder 101, and a drive controller 106 for driving an arm 23 in accordance with the decoded command. Also, it has a sensor circuit 105 for detecting the operation of the arm 23 through the drive controller 106, a reaction control subsystem (RCS) 107 for controlling the drive controller 106 to control the arm 23 to make a certain operation, a battery 104, and a propellant tank 103 for supplying fuel to the docking port 100 to drive it. The operation executing portion 21 also has the thruster 8b mounted like the management/control section 22. Fig. 10 schematically shows the management/control section 22 and operation executing portion 21.

The orbital space worker 14 has the following functions:

- To alter the orbit and carry or tow the materials when the materials are transported between the mother spaceship and the solar power satellite 11,
- To access to a target of the solar power satellite 11,
- To make docking and berthing with other units,
- To assemble and maintain the units
- To check and examine the solar power satellite itself, units and parts of units,
- To make a diagnosis and servicing of the solar power satellite and other solar power satellites; and
- To cooperate with spaceman.

Fig. 11 shows the operation of the orbital space worker 14. In this case, two operation executing portions 21 are ordered to carry the structure unit 8 by one management/control portion 22.

As described above, the orbital space worker 14 is comprised of the operation executing portion 21 and the management/control portion 22 as shown in Figs. 9 and 10. However, the operation executing portion 21 can be directly operated as an orbital space worker from an operator in a space station. Also, in the case that the operation executing portion 21 and the management/control portion 22 cannot work themselves so that the communication is not carried out from the central control station, a additional communication unit is used as a spacecraft having an independently operated function by arranging around the orbital space worker 14.

Accordingly, the orbital space worker 14 is of the disperse-type spacecraft and one of example of the virtually connected spacecraft system.

As described above, these dispersion-type space-crafts are complicated in their operations, but excellent in the possibility of extension, maintainability, realization expectancy since the respective units have independently operated functions. In other words, the constructed portions can be operated before the completion of all portions, and thus the period from the start of construction to the start of operation can be shortened. In addition, since units can be added or changed, the construction can be tried again and the maintenance is easy.

The units each having a function constituting the solar power satellite 11 mentioned with reference to Figs. 5 to 11 are horizontally thrown into orbit. The order of operation in which the units are connected in this way can be called the virtually connected spacecraft system.

The virtually connected spacecraft system has been described above in which the units each having a function are horizontally thrown into orbit. The transform spacecraft system in which the units each having a function are thrown from the mother spaceship so as to be vertically arranged. The orbital space worker 14 based on the transform spacecraft system is shown in Figs. 12, 13 and 14.

Referring to Fig. 12, there is shown a system dock 25 which is housed in the mother spaceship. The system dock has a plurality of units. The units are thrown into orbit from the system dock 25 when assembling into the orbital space worker 14. The units mainly include the command unit 12, a communication unit 25a, a attitude control unit 25b, propulsion unit 25c, a worker body 14a and a data processor unit 25e. These units are thrown from the system dock 25 into orbit, and then connected in the vertical direction as an operation configuration 26. As illustrated in Fig. 12, the units except the propulsion unit 25c are moved in parallel and connected. The connection of the units is performed by the command from the command unit 12 to each unit. The orbital space worker 14 is formed by the combination of these units.

Fig. 13 shows a plurality of units housed in the system dock 25 for constructing the orbital space worker 14. These units are a worker mooring truss unit 200, a propulsion unit 201 including a propellant tank and a reaction control subsystem (RCS), a thruster, a core unit 202 including an antenna, a transponder, a data processor, a power supply and a battery, an extension power supply unit 203 including a paddle 119, a power controller and a large battery, a worker control unit 204 including an antenna 24, a transponder, a data processor/controller, a sensor circuit and a stereo camera, a worker arm unit 205 including an arm 23, an arm controller and a sensor circuit, a docking unit 206 including a docking port, and an extension propellant tank unit 207 including a large propellant tank.

Figs. 14A, 14B and 14C show the units connected in the vertical direction. The units are vertically connected by the orbital space worker 14. In other words, the orbital space worker itself is a group of a plurality of units, and the orbital space worker 14 with the units con-

nected carries out the connecting operation. Fig. 14A shows a part of the orbital space worker which has the worker mooring truss unit 200, the worker control block 204 and the extension power supply block 203 connected in the vertical direction. Fig. 14B shows the orbital space worker 14 itself which has the propulsion unit 201, the core unit 202, the extension power supply unit 203, the worker control unit 204 and the worker arm unit 205 connected in the vertical direction. Fig. 14C shows the small-sized orbital space worker 14 which has the propulsion unit 201, the core unit 202, the worker arm unit 205 and the docking unit 206 connected in the vertical direction.

The above-mentioned transform spacecraft system is able to realize orbital space workers with various different functions by a combination of a plurality of units, if necessary and thus it is a highly efficient system. The transform spacecraft system has the following advantages.

- The units, upon failure, can be repaired and exchanged with ease.
- The optimum configuration of spacecraft can be selected in accordance with the mission.
- The consumption of fuel and materials can be reduced to the minimum.

The idea of the transform spacecraft system can be applied to an extremely small microrobot for use in the space, which has been demanded to develop.

The transform spacecraft system which can be realized as another embodiment of the present invention is described below.

Figs. 15 and 16 show the units of the spacecraft 30 of the transform spacecraft system for an experiment. Fig. 15 shows a plurality of units. These units include a command unit 31 for receiving the command from the mother spaceship and supplying a command to other units, two propulsion units 32 and 33 for the movement in the orbit and access to a target, an extension power supply unit 34 for backup, a data processor unit 35 for discriminating the commands received by the command unit 31, and a robot 36 having an arm and so on. These units are launched together from the earth into an orbit in outer space. Fig. 16 shows the spacecraft 30 launched into an orbit. The spacecraft 30 can be comprised of a small-scale satellite including plural units. This spacecraft 30 carries out the following experiments:

- To change the units,
- To make manipulation operation by robot 36,
- To make docking and berthing, and
- To tow the payload.
- The experiments for the transform spacecraft system will be described with reference to Fig. 17. The spacecraft 30 is launched by a rocket into outer space so as to orbit with the paddle and antenna opened. This is performed as the spreading experiment. On the other hand, the structure unit 30a as

materials are launched by a rocket into the orbit. The structure unit 30a is unfolded, or extended to a certain size since it is of a lling structure. This is also executed as the spreading experiment. Then, the spacecraft 30 and the structure unit 30a have a rendezvous with each other. A proper time after the rendezvous experiment, the spacecraft 30 is separated into four portions and combined with the structure 30a. In other words, the units of the spacecraft 30 is separated into four parts, the propulsion units 32, 33, the extension power supply unit 34, the command unit 31 and data processor unit 35, and the propulsion units 32, 33 and a robot 36. Then, the extension power supply unit 34 is assembled into one side of the structure unit 30a, the command unit 31 and data processor unit 35 into the other side of the structure unit 30a, and the propulsion units 32, 33 and the robot 36 into the central portion of the structure unit 30a. The combination is assumed to be called the spacecraft 30b. The propulsion units 32 and 33 are left separated. The operation is performed as the experiment for the separation, reconfiguration and docking. Thereafter, the spacecraft 30b is towed by the propulsion units 32 and 33, or experimented for tow. After the end of the tow experiment, the propulsion units 32, 33 and the robot 36 are separated from the spacecraft 30b, or the experiment for separation and reconfiguration are carried out. Then, the robot 36 separates the extension power supply unit 34, the command unit 31 and the data processor unit 35 from the structure unit 30a and combines the extension power supply unit 34, the command unit 31, the data processor unit 35 and the propulsion units 32, 33 in the vertical direction into a single unit, or the manipulation experiment is carried out. At this time, the robot 36 is also similarly assembled. The combination is assumed to be called a spacecraft 30c. The so-called transform spacecraft system is experimented. Then, the berthing experiment is carried out between the spacecraft 30c and the structure unit 30a, and the tow experiment for the structure unit 30a is performed by the spacecraft 30c. The residual substances left after the assembly of the spacecraft 30c are moved together with the structure unit 30a.

The experiment for the virtually connected spacecraft system will be mentioned below. Fig. 18 again shows the robot 36 illustrated in Fig. 10. The robot 36 shown in Fig. 18 is formed of the management/control portion 22 and the operation executing portion 21. The management/control portion 22 is fundamentally the same as the construction shown in Fig. 9, and has the antenna 24 and paddle 119 extended from the body. On the other hand, the operation executing portion 21 is fundamentally the same as the construction shown in Fig. 9, and has the arm 23 extended from the body. The following experiments are carried out by use of the orbital space worker 14:

- The confirmation of how to operate the orbital space worker 14,
- The confirmation of how to supply propellant,
- The confirmation of how to charge batteries,
- The attitude control of the flexible structures,
- The orbital control of the flexible structure,
- The rendezvous and docking of the flexible structures,
- The cooperative control of spacecrafsts,
- The cooperative operation of spacecrafsts, and
- The handling of large spread type structures

The experiments for the virtually connected spacecraft system will be described with reference to Fig. 19. The management/control portion 22 and operation executing portion 21 are launched together by a rocket into an orbit in outer space. Then, the paddle 119 and so on are first experimented for unfolding, and the arm 23 and thruster 8b of the operation executing portion 21 are experimented for their operation. In addition, the operation executing portion 21 and the management/control portion 22 are experimented for separation, and the operation executing portion 21 is experimented as to whether it can operate swiftly and easily or not. The operation executing portion 21 is made close to the structure unit 8, and the remote control experiment is carried out as to whether or not the manipulator such as arm 23 can operate satisfactorily. Thereafter, the docking experiment for the operation executing portion 21 and the management/control portion 22 is carried out and the propellant supply and battery charging experiments are performed. Finally, the detailed functions of the operation executing portion 21 and the management/control portion 22 are experimented.

Fig. 20 shows an example of the transport of the structure unit 8 by the cooperation of the operation executing portion 21 and the management/control portion 22. Fig. 21 shows another example of the transport of the flexible structure 8d by the operation executing portion 21.

Fig. 22 shows an example of the experiment for the flexible structure 8d. This experiment will be described below. The flexible structure 8d in a compressed state is launched by a rocket into an orbit in outer space, and then the unfolding experiment is performed. The structure unit 8 in a compressed state is also launched by a rocket into the orbit, and experimented for the unfolding operation. The flexible structure 8d and the structure unit 8 are, after the end of the rendezvous experiment, experimented for the docking operation. In this experiment, the rotating table, 8e of the flexible structure 8d is connected to a certain place of the structure unit 8. This docking experiment is absolutely necessary for the construction of the solar power satellite. Then, the flexible structure 8d is experimented for its separation from the structure unit 8, and the docking experiment is performed for the structures. Thereafter, the flexible structure 8d is tested for its rotation around the rotating table 8e. In addition, the pointing test is carried out as to whether or not the

surface of the flexible structure 8d is, for example, perpendicular to the ray from the sun. This experiment is the most important when the flexible structure 8d is such as an unfoldable, or spreadable array.

The spacecraft system called the follow-on mission will be described below. The follow-on mission is used to prevent that the floating spacecrafsts and so on used for the experiments disturb the space environment. In addition, this follow-on mission is used to effectively utilize the floating old spacecrafsts such as communication satellites which closed their lives in order that these old spacecrafsts can be prevented from interfering with the other spacecrafsts. As the follow-on mission, an unmanned space laboratory base can be considered which utilizes the floating residues such as the old spacecrafsts which closed their lives. Fig. 23 shows major units of an unmanned space laboratory base 40. Of these units, the orbital space worker 14 and the material storehouse 15 are selected from the residues of the solar power satellite, and the power generating unfolding-type array unit 41, the extension-type truss unit 42, and the cooling unfolding-type radiator unit 43 as additional units are launched from the earth into an orbit in outer space. Fig. 24A and 24B show constructed unmanned space laboratory base 40. The orbital space worker 14 is used for the construction and maintenance of the unmanned space laboratory base 40.

Fig. 25 shows one example of the construction of the unmanned space laboratory base 40. The unmanned space laboratory base 40 is constructed by the combination of the flexible structure 8d, rotating table 8e and structure unit 8 used in the experiment of the virtually connected spacecraft system previously described with reference to Fig. 22, the orbital space worker 14 and the additional units launched into the orbit. In addition, Fig. 26 shows the recovery of the waste products resulting from the experiment by the recovery capsule 40b after the construction of the space experimenting apparatus 40a. In other words, the orbital space worker 14 separates the recovery capsule 40b which collected the waste products, from the space experiment testing apparatus 40a, and the recovery capsule 40b is recovered back to the ground. In this way, it is possible to construct the spacecraft system which has the possibility of extension, maintainability, and realization expectancy.

## Claims

1. A system of spacecrafsts launched into outer space to execute cooperative operations, comprising:  
a plurality of spacecrafsts (1a, 1b, 1c; 30) each including at least a propulsion means for driving the spacecrafst itself,  
communication means (2a, 2b, 2c), and mission performing means (10, 12, 13) for performing at least one operation function;  
**characterized in that**  
the spacecrafst system further comprises a central control means for operating said spacecrafsts in

5  
10  
15  
accordance with said mission performing means through said communication means in which each of said plurality of spacecrafsts communicate with one another through said communication means on the basis of a command from said central control means, and actuate said propulsion means, and cooperatively treat a mission object (8, 30a) launched and floated in outer space by assembling, maintaining, repairing and/or collecting the mission object or a single structural facility thereof on the basis of a predetermined project.

2. A spacecraft system according to claim 1, wherein said mission object includes construction materials (8) and/or electric materials (9) and/or mechanical materials (15) and/or chemical materials (16) and/or waste products (40b) and/or subsistence goods and/or research materials.
3. A spacecraft system according to claim 1, wherein said spacecrafsts house an orbital working (14).
4. A spacecraft system according to claim 1, further comprising a space repeater which communicates with said spacecrafsts.
5. A spacecraft system according to claim 1, wherein said mission means is formed of a plurality of units (8, 9, 10, 12, 13) which are provided for respective operation functions and can be separated from said spacecrafsts.
6. A spacecraft system according to claim 5, wherein said plurality of units include at least a command unit (12), a power generation unit (9), a structure unit (8), an orbital working means (14), a communication unit (25a), an attitude control unit (25b), a propulsion unit (25c), a data processing unit (25e), a material storehouse (15), a propellant unit depot (16) and an extension power supply unit (34).
7. A spacecraft system according to claim 3, wherein said orbital working means (14) has a manipulator (23) and includes at least a communicating portion (22), a propulsion portion (8b) for driving said working means itself and a drive (106) for driving said manipulator.
8. A spacecraft system according to claim 2, wherein said mission object includes a solar power generator (11) having a photosensitive portion (9) for receiving solar energy, a power transmitting portion (5) for transmitting electric power from said photosensitive portion to the ground, and a structure (8) for mounting said photosensitive portion and said power transmitting portion.
9. A spacecraft system according to claim 2, wherein said mission object includes a structure, apparatus,

materials to be used in an unmanned space laboratory base (40) and a space laboratory equipment.

10. A spacecraft system according to claim 2, wherein said mission object includes at least a body (14a) of said orbital working means, said communication unit (25a), said attitude control unit (25b), said propulsion unit (25c) and said data processing unit (25e), whereby the body (14a) of the units (25a-25e) are operable to be released into orbit and combined to the orbital working means (14).

11. A spacecraft system according to claim 1, wherein said mission object includes old spacecrafts which closed their lives.

12. A spacecraft system according to claim 1, wherein said central control means includes a ground control station.

13. A spacecraft system according to claim 1, wherein said central control means includes a space control station.

14. A spacecraft system according to claim 10, wherein said orbital working means is used for combining at least a command unit (12), a power generation unit (9), a structure unit (8), a material store house (15), a propellant depot unit (16), an extension power supply unit (34), an attitude control unit (25b), a propulsion unit (25c) and a data processing unit which are separated from said spacecrafts in accordance with a command from said central control means and said spacecrafts.

15. A spacecraft system according to claim 10, wherein said orbital working means is used for combining at least a communication unit (25a), an attitude control unit (25b), a propulsion unit (25c) and a data processing unit (25e) with said mission object.

16. A spacecraft system according to claim 10, wherein said orbital working means (14) is used for assembling said mission object (8) in cooperation with other orbital working means (14) of spacecrafts according to a command from said spacecraft in which said orbital working means is housed.

**Patentansprüche**

1. Raumfahrzeugsystem, das in den Weltraum gesandt wird, um kooperative Operationen durchzuführen, aufweisend:  
eine Vielzahl von Raumfahrzeugen (1a, 1b, 1c; 30) von denen jedes mindestens eine Antriebsvorrichtung zum Antreiben des Raumschiffes selber aufweist;  
Kommunikationseinrichtungen (2a, 2b, 2c) und Missionssdurchführungsvorrichtungen (10, 12, 13) zum Durchführen mindestens einer einzelnen Operationsfunktion;  
dadurch gekennzeichnet, daß das Raumfahrzeugsystem weiter eine zentrale Steuervorrichtung zum Betreiben der Raumfahrzeuge gemäß der Missionssdurchführungsvorrichtung durch die genannten Kommunikationseinrichtungen aufweist, wobei jedes der Mehrzahl der Raumfahrzeuge untereinander durch die genannten Kommunikationseinrichtungen auf der Basis eines Befehls der zentralen Steuervorrichtung kommunizieren und die genannte Antriebsvorrichtung betätigen, sowie kooperativ ein in den Weltraum gesandtes und darin bewegtes Missionssobjekt durch Zusammenbauen, Warten, Reparieren und/oder Einsammeln des Missionssobjektes (38a) oder einer einzelnen Strukturkomponente desselben auf der Basis eines vorbestimmten Projektes behandeln.

2. Raumfahrzeugsystem nach Anspruch 1, bei dem das Missionssobjekt Konstruktionsmaterialien (8) und/oder elektrische Materialien (9) und/oder mechanische Materialien (15) und/oder chemische Materialien (16) und/oder Abfallprodukte (40b) und/oder Lebenserhaltungsgüter und/oder Forschungsmaterialien umfaßt.

3. Raumfahrzeugsystem nach Anspruch 1, bei dem die Raumfahrzeuge eine orbitale Arbeitsvorrichtung (14) mitführen.

4. Raumfahrzeugsystem nach Anspruch 1, das weiter einen Weltraumrepeater umfaßt, der mit den Raumfahrzeugen kommuniziert.

5. Raumfahrzeugsystem nach Anspruch 1, bei dem die Missionssvorrichtung aus einer Mehrzahl von Einheiten (8, 9, 10, 12, 13) gebildet ist, die für entsprechende Operationsfunktionen vorgesehen sind und von den Raumfahrzeugen getrennt werden können.

6. Raumfahrzeugsystem nach Anspruch 5, bei dem die Mehrzahl der Einheiten mindestens eine Befehleinheit (12), eine Energierzeugungseinheit (9), eine Gerüsteinheit (8), eine orbitale Arbeitsvorrichtung (14), eine Kommunikationseinheit (25a), eine Fluglagensteuereinheit (25b), eine Antriebsseinheit (25c), eine Datenverarbeitungseinheit (25e), einen Materiallagerbehälter (15), eine Treibstoffflasche (16) und eine Nebeneinheit (34) umfaßt.

7. Raumfahrzeugsystem nach Anspruch 3, bei der die orbitale Arbeitsvorrichtung (14) einen Manipulator (23) aufweist und mindestens einen Kommunikationsteil (22), einen Antriebsteil (8b) zum Antreiben der Arbeitsvorrichtung selber, und einen Antrieb (106) zum Antreiben des Manipulators umfaßt.

8. Raumfahrzeugsystem nach Anspruch 2, bei dem das Missionsobjekt einen Solarenergiegenerator (11) mit einem lichtempfindlichen Teil (9) zum Empfangen von Solarenergie, einen Übertragungsteil (5) zum Übertragen elektrischer Energie vom lichtempfindlichen Teil zur Erde, und ein Gerüst (8) zum Montieren des lichtempfindlichen Teils und des energieübertragenden Teils aufweist. 5

9. Raumfahrzeugsystem nach Anspruch 2, bei dem das Missionsobjekt ein Gerüst, Vorrichtungen, Materialien zur Verwendung in einer unbemannten Weltraum-Laboratoriumsstation (40) sowie Welt-  
raum-Laboratoriumsausrüstungen umfaßt. 10

10. Raumfahrzeugsystem nach Anspruch 2, bei dem das Missionsobjekt mindestens einen Körper (14a) der orbitalen Arbeitsvorrichtung, die genannte Kom-  
munikationseinheit (25a), die genannte Fluglagen-  
steuereinheit (25b), die genannte Antriebseinheit  
(25c) und die genannte Datenverarbeitungseinheit  
(25e) umfaßt, wodurch der Körper (14a) und die Ein-  
heiten (25a-25e) betriebsfähig sind, um in die  
Umlaufbahn entlassen und mit der orbitalen Arbeits-  
vorrichtung (14) kombiniert zu werden. 15 20 25

11. Raumfahrzeugsystem nach Anspruch 1, bei dem das Missionsobjekt alte Raumfahrzeuge umfaßt, deren Lebensdauer zu Ende gegangen ist. 30

12. Raumfahrzeugsystem nach Anspruch 1, bei dem die zentrale Steuervorrichtung eine erdgebundene Steuerstation umfaßt. 35

13. Raumfahrzeugsystem nach Anspruch 1, bei dem die zentrale Steuervorrichtung eine Weltraumsteu-  
erstation umfaßt. 35

14. Raumfahrzeugsystem nach Anspruch 10, bei dem die orbitale Arbeitsvorrichtung zum Kombinieren von mindestens einer Steuereinheit (12), einer Energieerzeugungseinheit (9), einer Gerüsteinheit (8), einem Materiallagerbehälter (15), einer Treib-  
stofflagereinheit (16), einer Nebenversorgungsein-  
heit (34), einer Fluglagensteuereinheit (25b), einer Antriebseinheit (25c) und einer Datenverarbeitungs-  
einheit aufweist, die von den Raumfahrzeugen ent-  
sprechend einem Befehl der zentralen Steuervorrichtung und den Raumfahrzeugen getrennt werden. 40 45 50

15. Raumfahrzeugsystem nach Anspruch 10, bei dem die orbitale Arbeitsvorrichtung zum Kombinieren mindestens einer Kommunikationseinheit (25a), einer Fluglagensteuereinheit (25b), einer Antriebseinheit (25c) und einer Datenverarbeitungseinheit (25e) mit dem Missionsobjekt verwendet wird. 55

16. Raumfahrzeugsystem nach Anspruch 10, bei dem die orbitale Arbeitsvorrichtung (14) zum Zusammen-  
bauen des Missionsobjektes (8) in Kooperation mit anderen orbitalen Arbeitsvorrichtungen (14) von Raumfahrzeugen verwendet wird, und zwar gemäß einem Befehl des genannten Raumfahrzeugs, in welchem die orbitale Arbeitsvorrichtung unterge-  
bracht ist. 5

### Revendications

1. Système de véhicules spatiaux lancés dans l'espace pour exécuter des opérations en coopération, comprenant :  
une pluralité de véhicules spatiaux (1a,1b,1c;30) comprenant chacun au moins un moyen de propulsion pour entraîner le véhicule spatial lui-même,  
des moyens de communication (2a,2b,2c) et des moyens (10,12,13) d'exécution de mission pour exécuter au moins une fonction opérationnelle,  
caractérisé en ce que  
le système de véhicules spatiaux comprend des moyens centraux de commande pour faire fonctionner lesdits véhicules spatiaux en fonction desdits moyens d'exécution de mission à l'aide desdits moyens de communication, chacun de ladite pluralité de véhicules spatiaux communique avec les autres véhicules spatiaux par l'intermédiaire desdits moyens de communication sur la base d'un nombre délivré par lesdits moyens centraux de commande, actionne ledit moyen de propulsion, et traite en coopération un objet de mission (8,30a) lancé et flottant dans l'espace, par assemblage, maintenance, réparation et/ou récupération de l'objet de mission, ou d'un seul équipement structurel de cet objet sur la base d'un projet prédéterminé.

2. Système de véhicules spatiaux selon la revendication 1, dans lequel ledit objet de mission comprend des matériels de construction (8) et/ou des matériels électriques (9) et/ou des matériels mécaniques (15) et/ou des substances chimiques (16) et/ou des déchets (40b) et/ou des denrées de subsistance et/ou des matériels de recherche.

3. Système de véhicules spatiaux selon la revendication 1, dans lequel lesdits véhicules spatiaux logent des moyens de travail en orbite (14).

4. Système de véhicules spatiaux selon la revendication 1, comprenant en outre un poste relais spatial qui communique avec lesdits véhicules spatiaux.

5. Système de véhicules spatiaux selon la revendication 1, dans lequel lesdits moyens de mission sont formés par une pluralité d'unités (8,9,10,12,13), qui sont prévues pour des fonctions opérationnelles

respectives et peuvent être séparées desdits véhicules spatiaux.

6. Système de véhicules spatiaux selon la revendication 5, dans lequel ladite pluralité d'unités comprennent au moins une unité de commande (12), une unité de production d'énergie (9), une unité de structure (8), des moyens de travail en orbite (14), une unité de communication (25a), une unité de commande d'attitude (25b), une unité de propulsion (25c), une unité de traitement de données (25d), un magasin de stockage de matériel (15), un dépôt d'agent propulsif (16) et une unité d'alimentation en énergie supplémentaire (34).

7. Système de véhicules spatiaux selon la revendication 3, dans lequel lesdits moyens de travail en orbite (14) possèdent un manipulateur (23) et comprennent au moins une partie de communication (22), une partie de propulsion (8b) pour entraîner lesdits moyens de travail eux-mêmes et une unité d'entraînement (106) pour entraîner ledit manipulateur.

8. Système de véhicules spatiaux selon la revendication 2, dans lequel ledit objet de mission comprend un générateur solaire (11) possédant une partie photosensible (9) servant à recevoir l'énergie solaire, une partie de transmission de puissance (5) pour transmettre une puissance électrique depuis ladite partie photosensible à la terre et une structure (8) pour le montage de ladite partie photosensible et de ladite partie de transmission de puissance.

9. Système de véhicules spatiaux selon la revendication 2, dans lequel ledit objet de mission comprend une structure, des dispositifs et des matériaux devant être utilisés dans une base de laboratoire spatial inhabitée (40) et un équipement de laboratoire spatial.

10. Système de véhicules spatiaux selon la revendication 2, dans lequel ledit objet de mission comprend au moins un corps (14a) desdits moyens de travail en orbite, ladite unité de communication (25a), ladite unité de commande d'attitude (25b), ladite unité de propulsion (25c) et ladite unité de traitement de données (25e), le corps (14a) des unités (25a-25e) pouvant être actionné de manière à être libéré en orbite et combiné aux moyens de travail en orbite (14).

11. Système de véhicules spatiaux selon la revendication 1, dans lequel ledit objet de mission comprend des anciens véhicules spatiaux dont la durée de vie est terminée.

12. Système de véhicules spatiaux selon la revendication 1, dans lequel lesdits moyens centraux de commande comprennent une station de commande au sol.

13. Système de véhicules spatiaux selon la revendication 1, dans lequel lesdits moyens centraux de commande comprennent une station de commande spatiale.

14. Système de véhicules spatiaux selon la revendication 10, dans lequel lesdits moyens de travail en orbite sont utilisés pour combiner au moins une unité de commande (12), une unité de production d'énergie (9), une unité de structure (8), un magasin (15) de stockage de matériaux, un dépôt d'agent propulsif, une unité d'alimentation en énergie supplémentaire (34), une unité de commande d'attitude (25b), une unité de propulsion (25c) et une unité de traitement de données, qui sont séparées desdits véhicules spatiaux en fonction d'un ordre provenant desdits moyens centraux de commande et desdits véhicules spatiaux.

15. Système de véhicules spatiaux selon la revendication 10, dans lequel lesdits moyens de travail en orbite sont utilisés pour combiner au moins une unité de communication (25a), une unité de commande d'attitude (25b), une unité de propulsion (25c) et une unité de traitement de données (25e) avec ledit objet de mission.

16. Système de véhicules spatiaux selon la revendication 10, dans lequel lesdits moyens de travail en orbite (14) sont utilisés pour assembler ledit objet (8) de mission en coopération avec d'autres moyens de travail en orbite (14) de véhicules spatiaux en fonction d'un ordre provenant dudit véhicule spatial, dans lequel sont logés lesdits moyens de travail en orbite.

FIG. 1

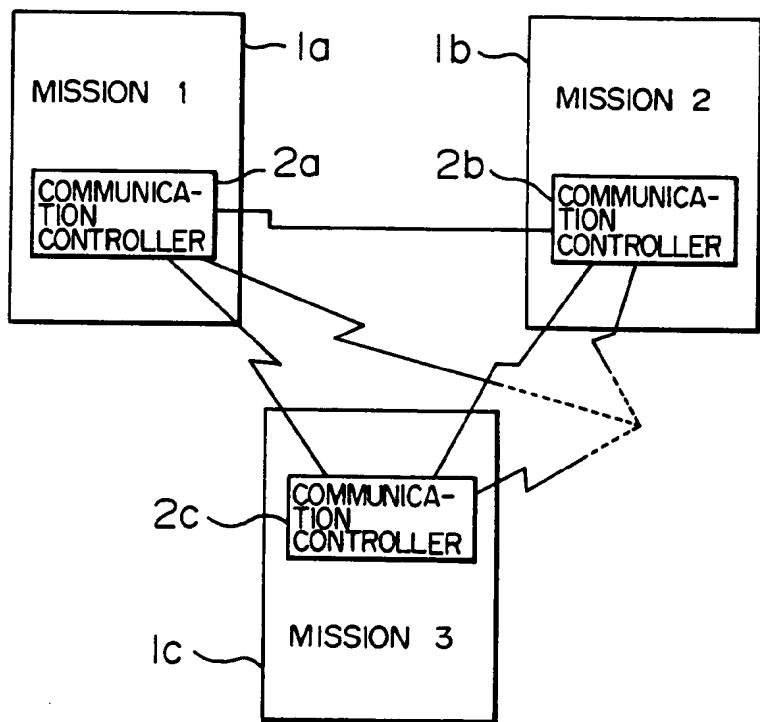


FIG. 2

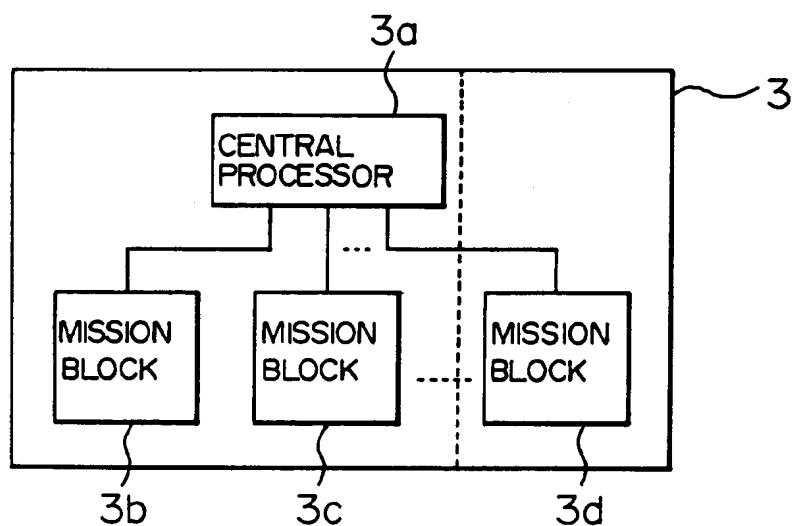


FIG. 3

EXTENSI- BILITY	MAINTAIN- ABILITY	OPERABILITY	REALIZATION EXPECTANCY
CONFIGURATION OF DIVISION-TYPE SPACECRAFT	×	○	EASINESS OF CON- STRUCTION
CONFIGURATION OF DISPERSION- TYPE SPACECRAFT	○	○	EASINESS TO OPERATION
			REALIZATION EXPECTANCY

Legend:

- : EASINESS
- ×: DURABILITY
- △: PARTIAL OP-  
ERATION CAN  
BE CARRIED OUT

FIG. 4

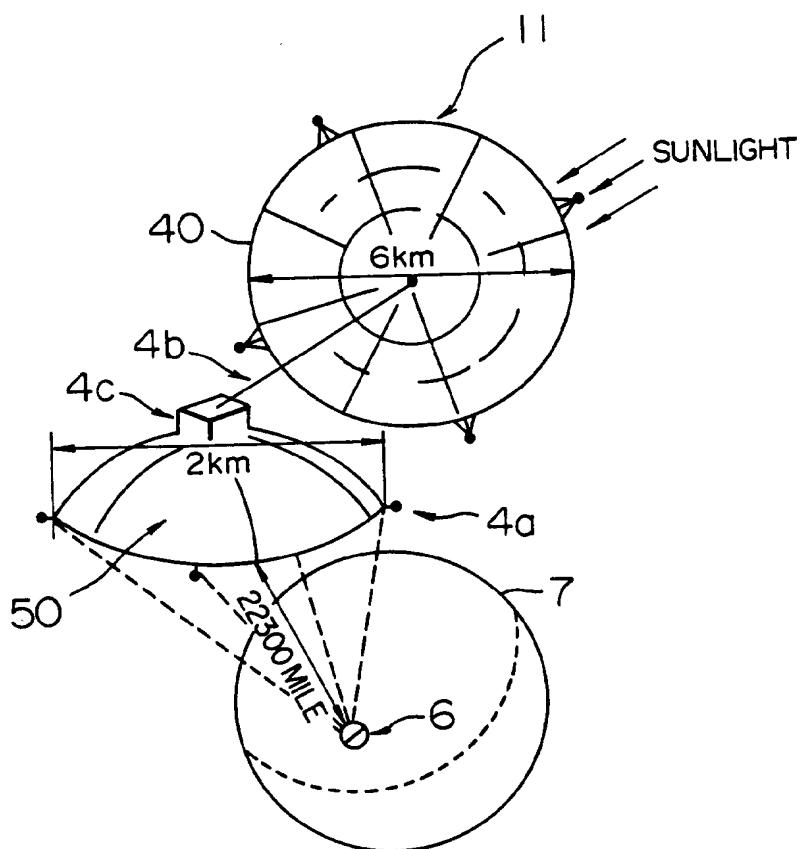


FIG. 5A

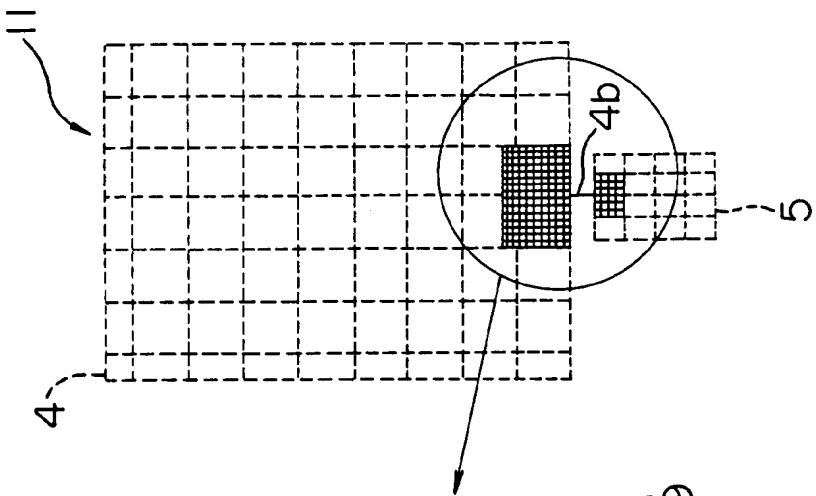


FIG. 5B

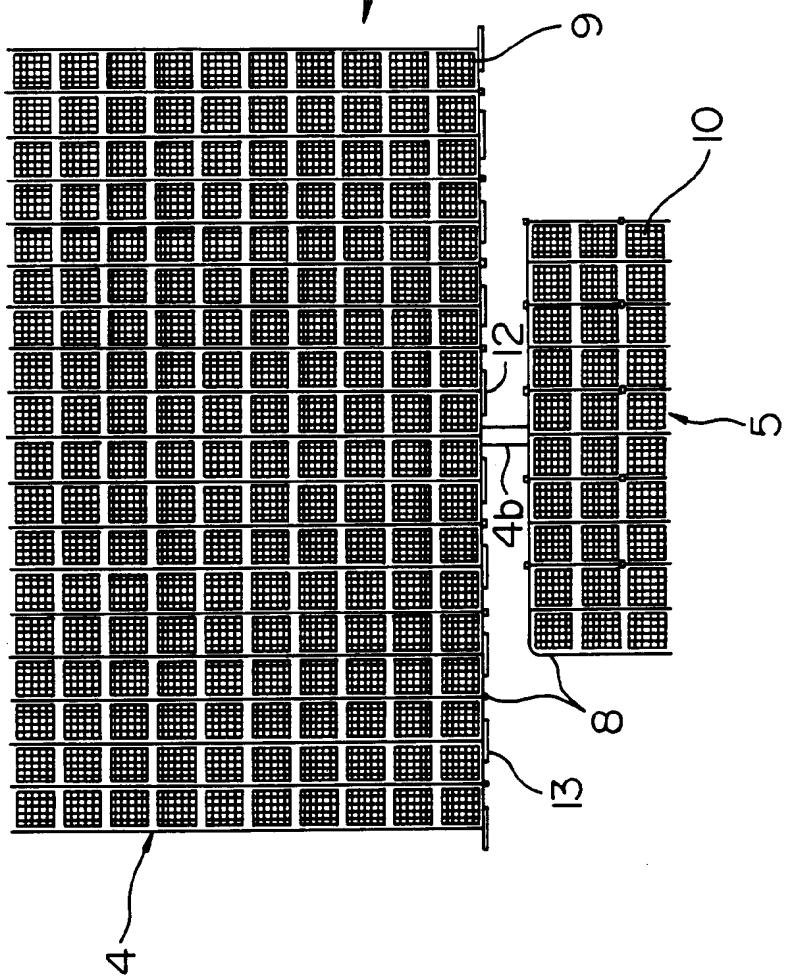


FIG. 6

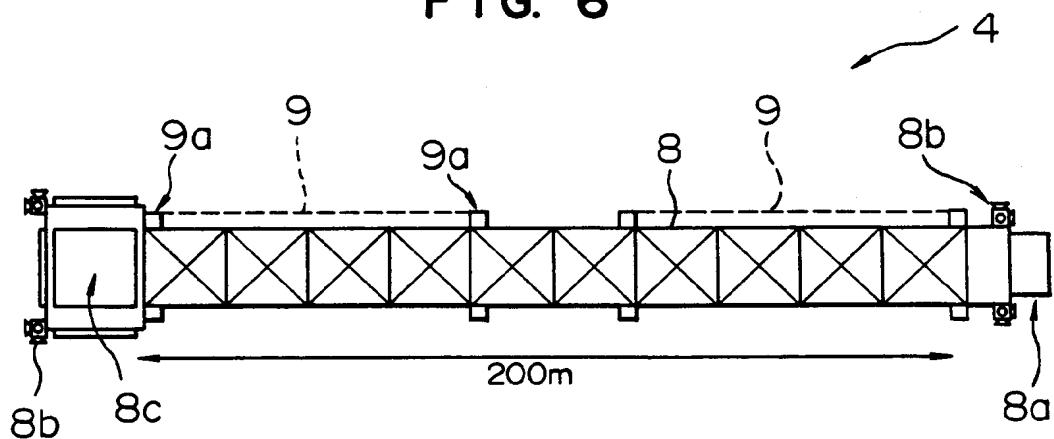


FIG. 7

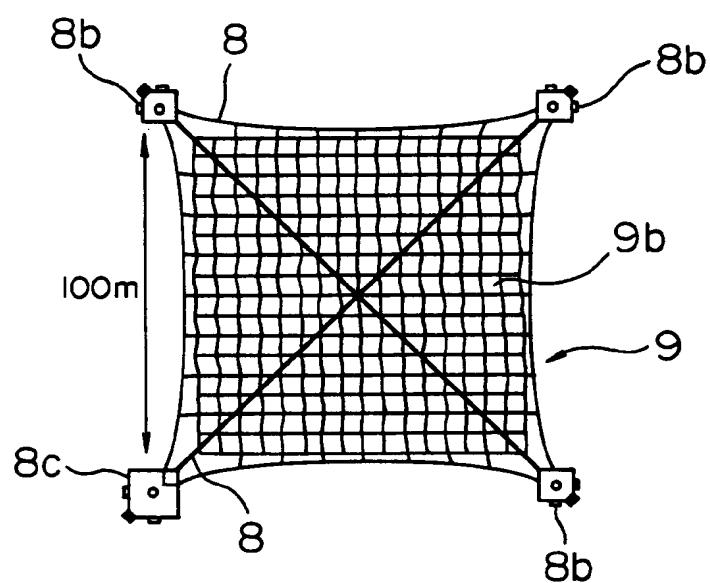


FIG. 8

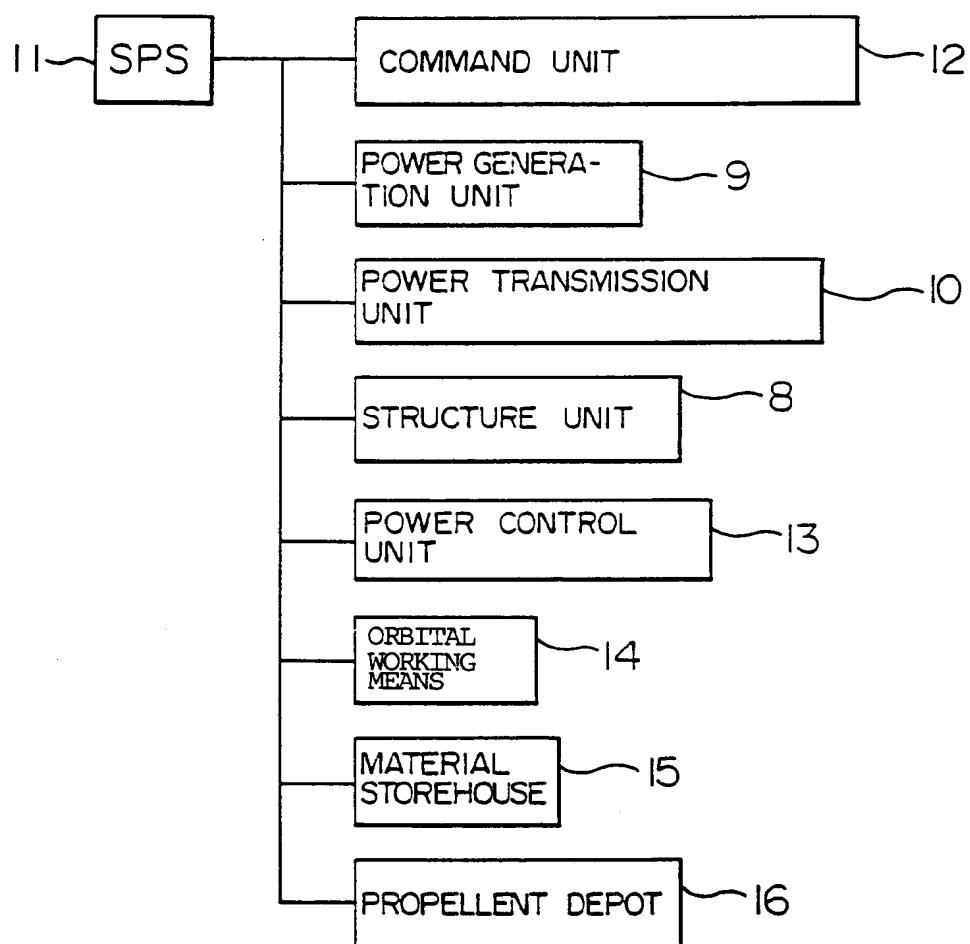


FIG. 9

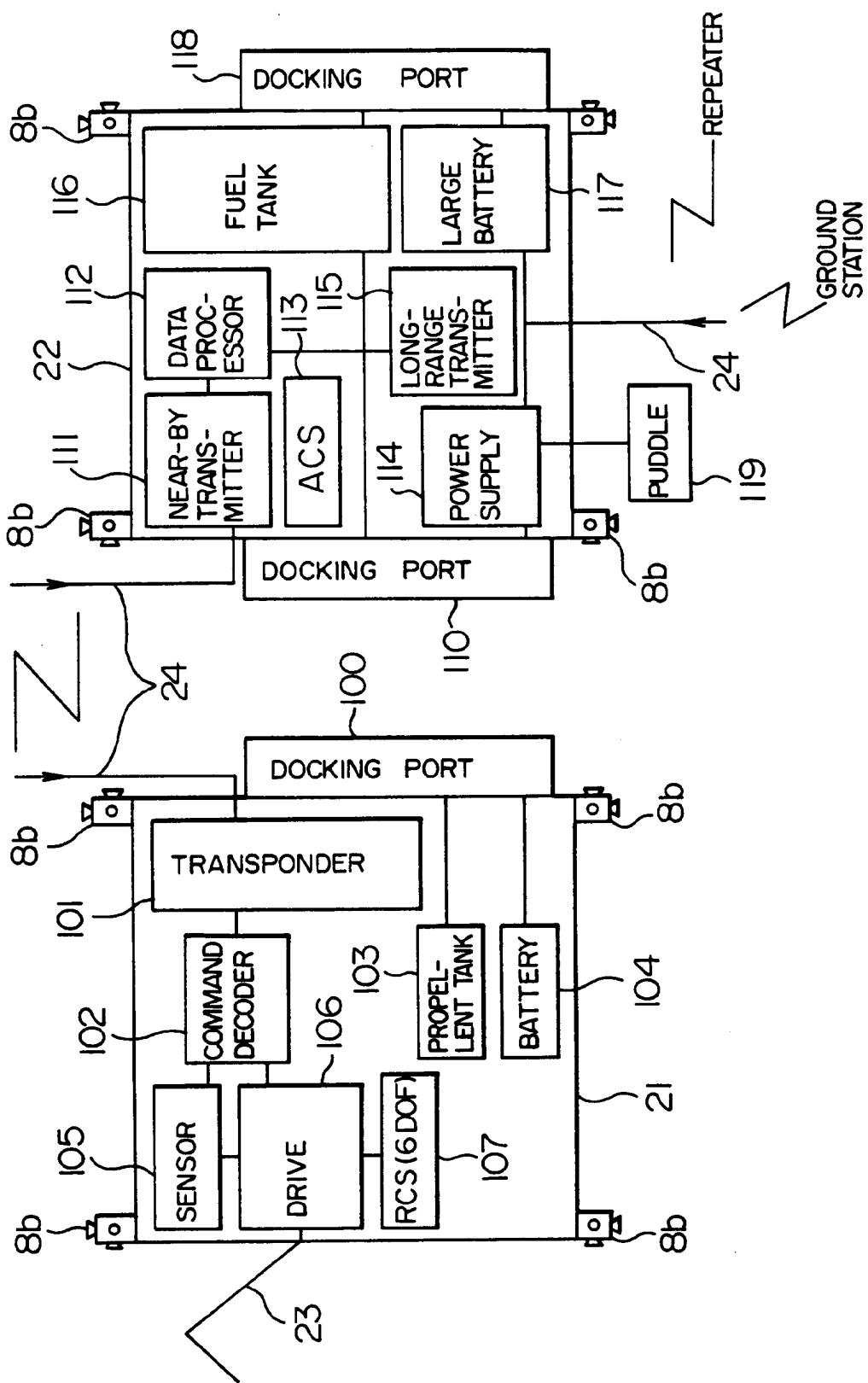


FIG. 10

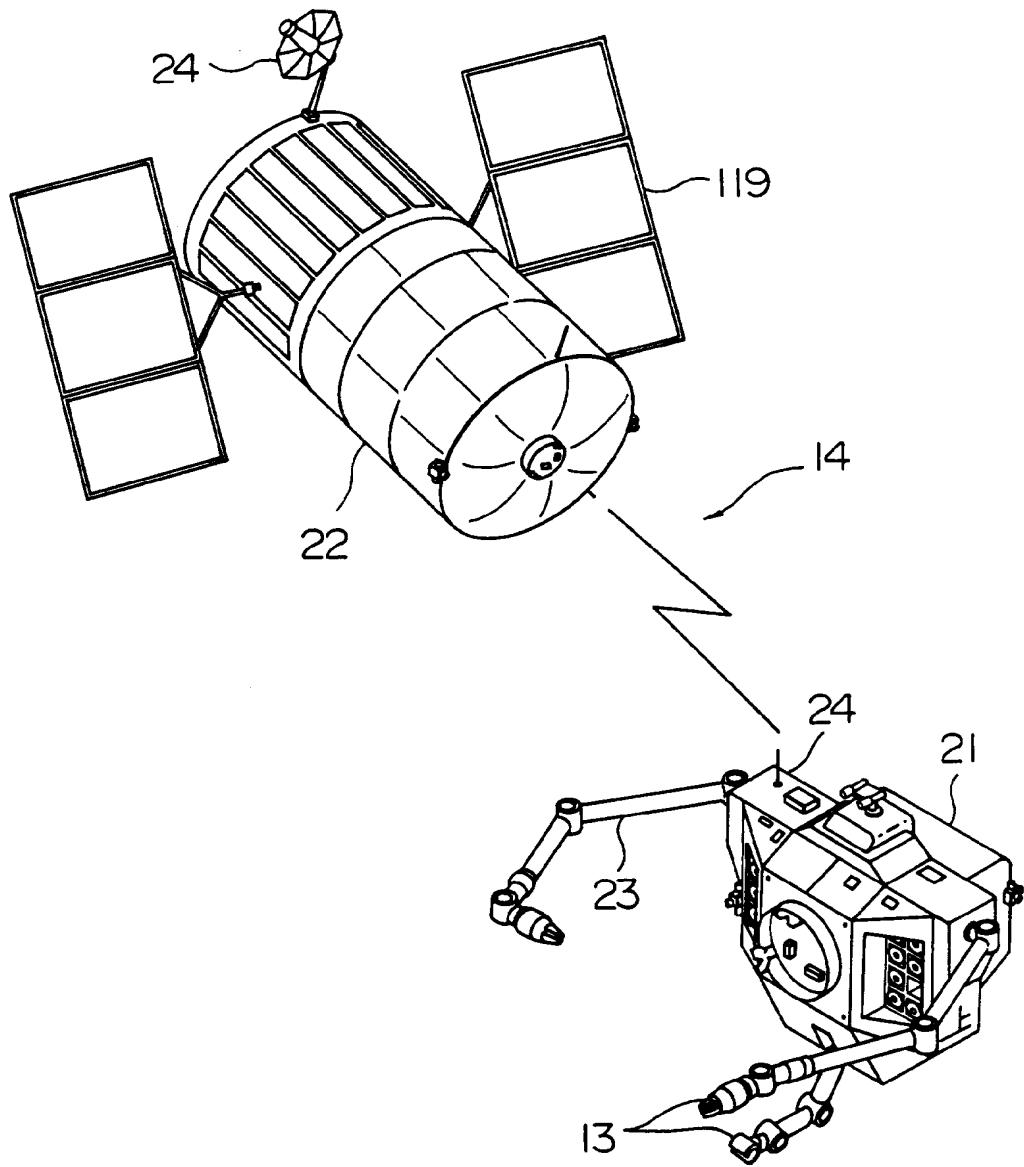


FIG. 11

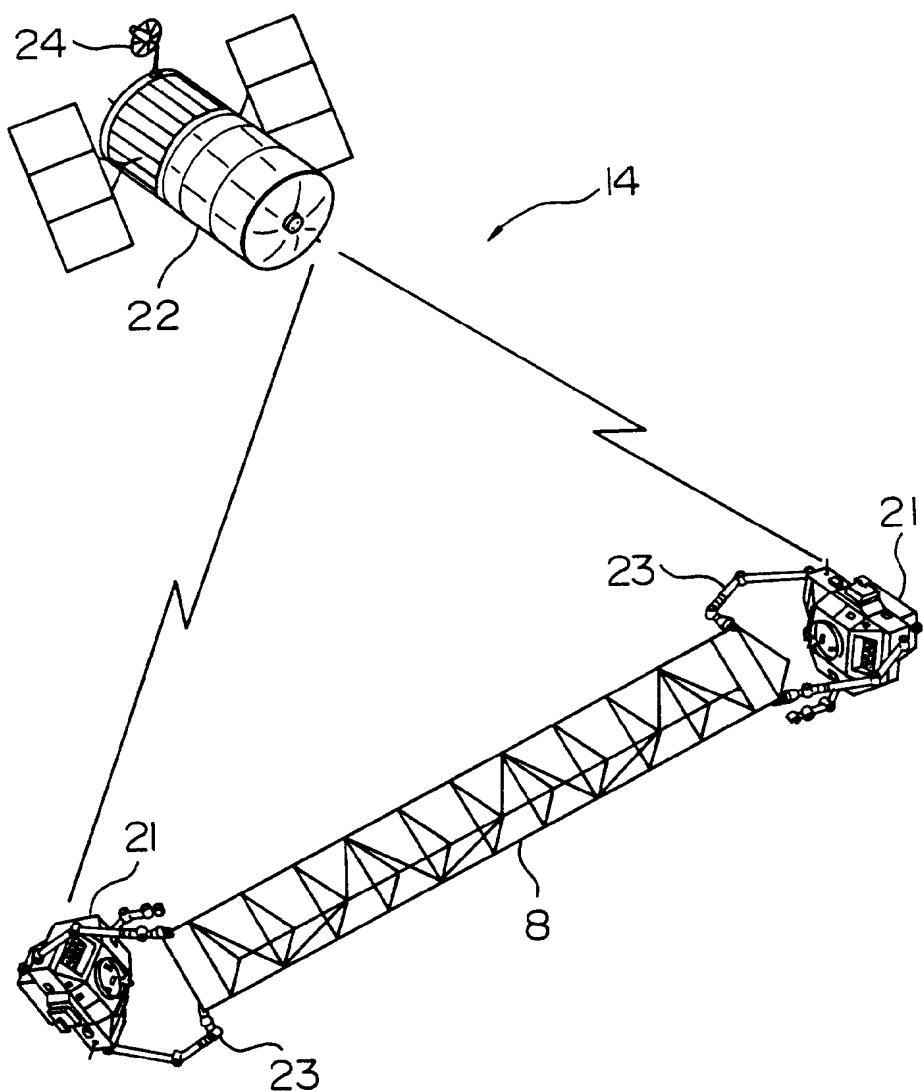


FIG. 12

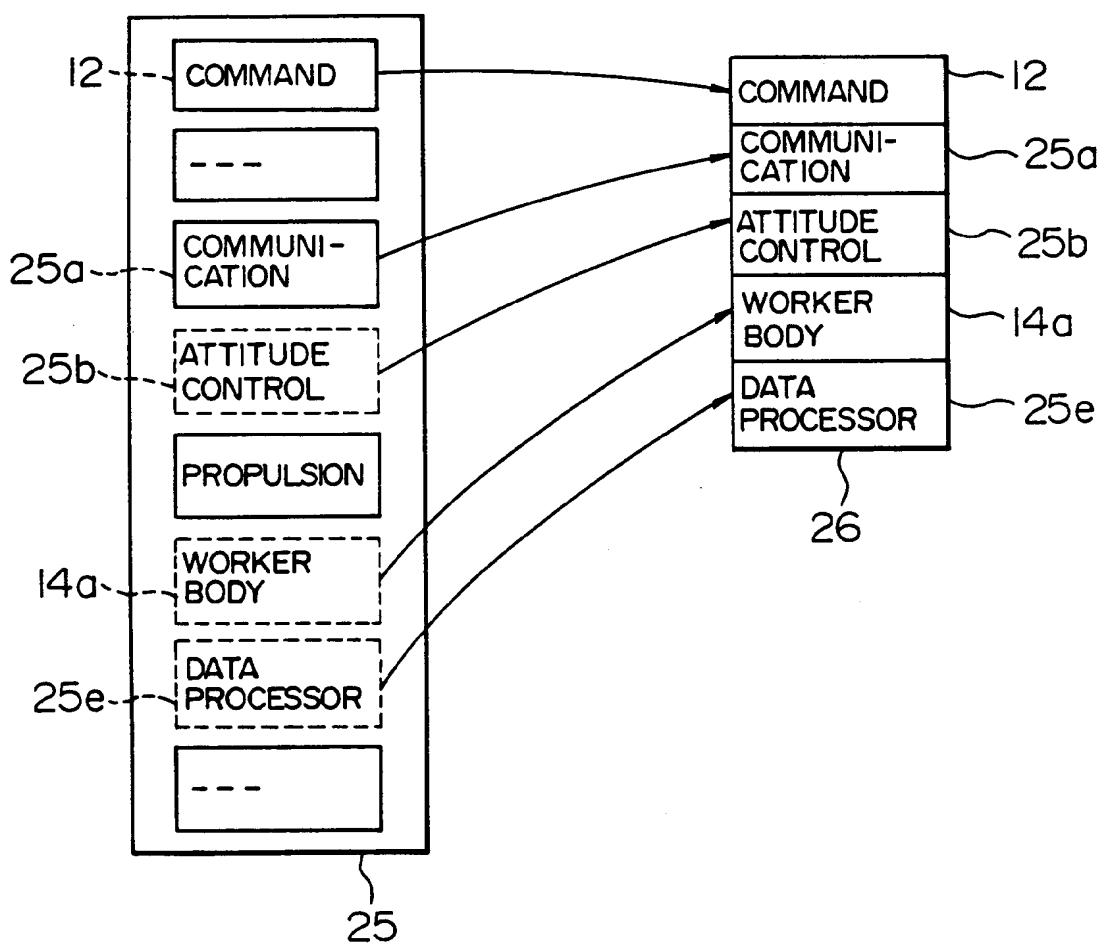


FIG. 13

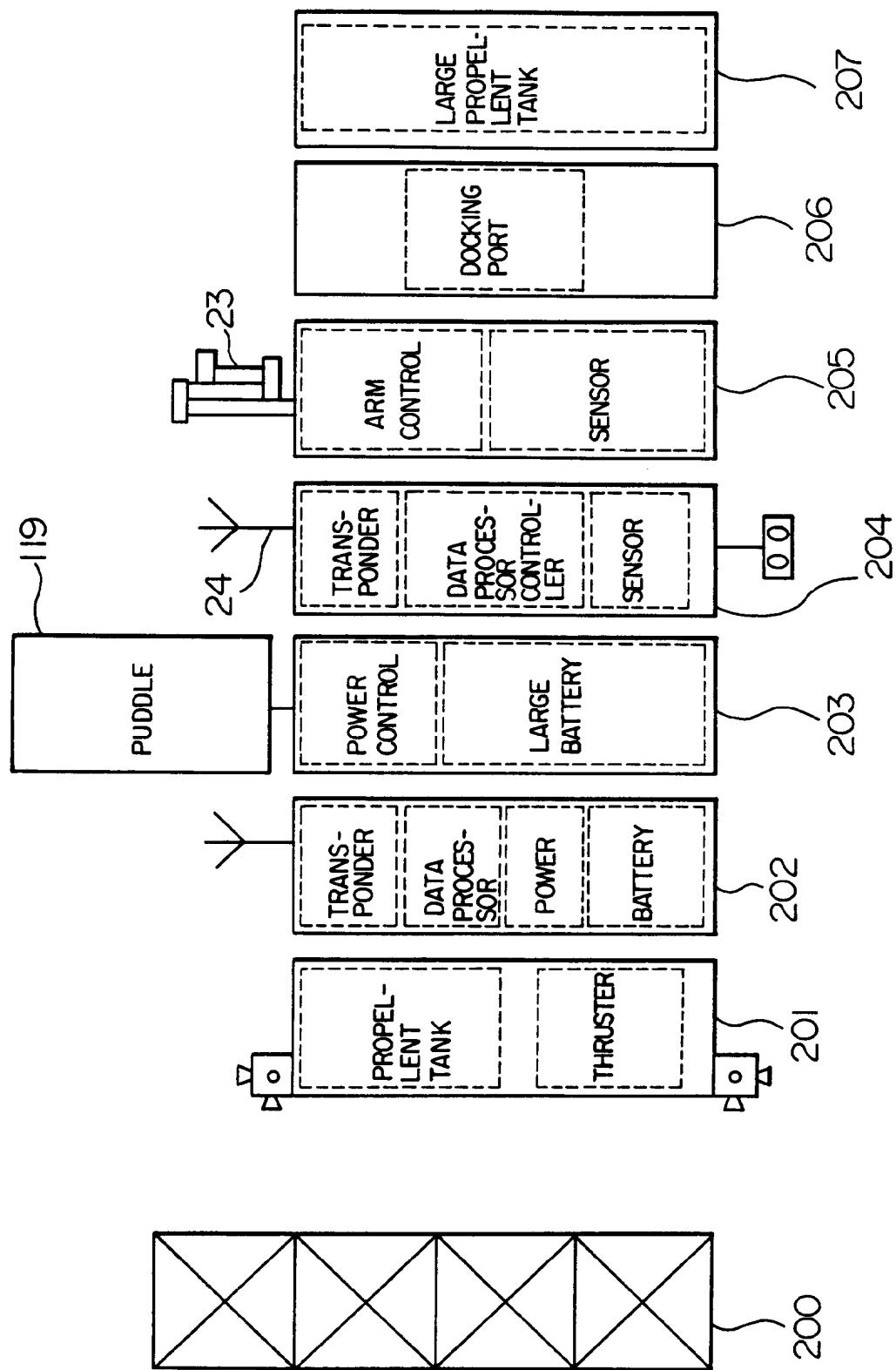


FIG. 14A

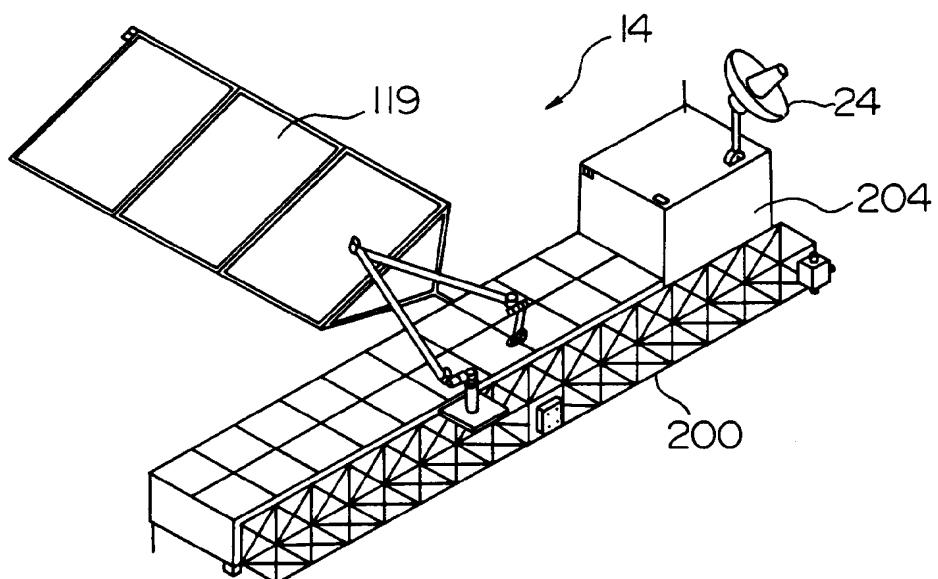


FIG. 14B

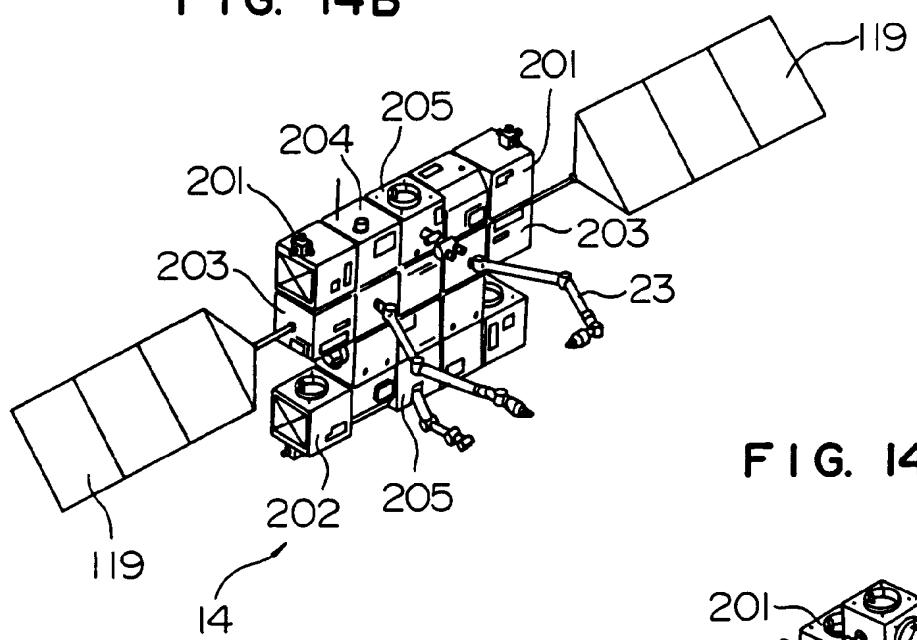


FIG. 14C

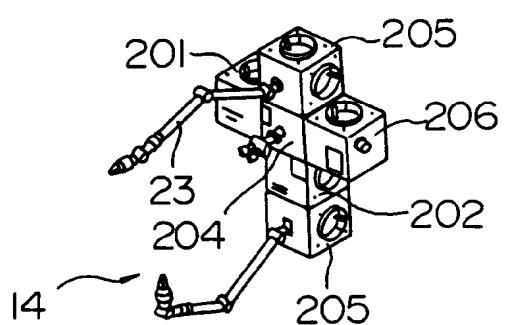
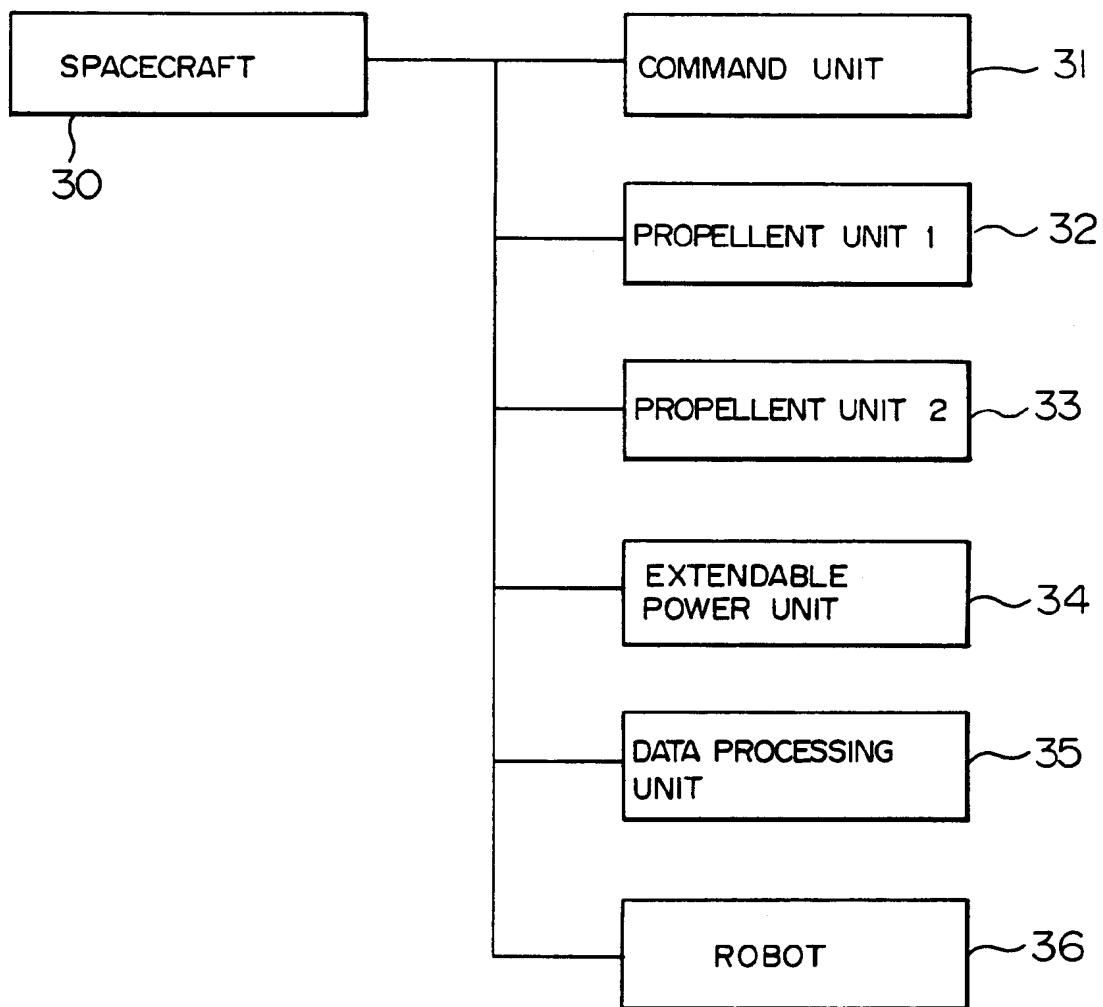


FIG. 15



## FIG. 16

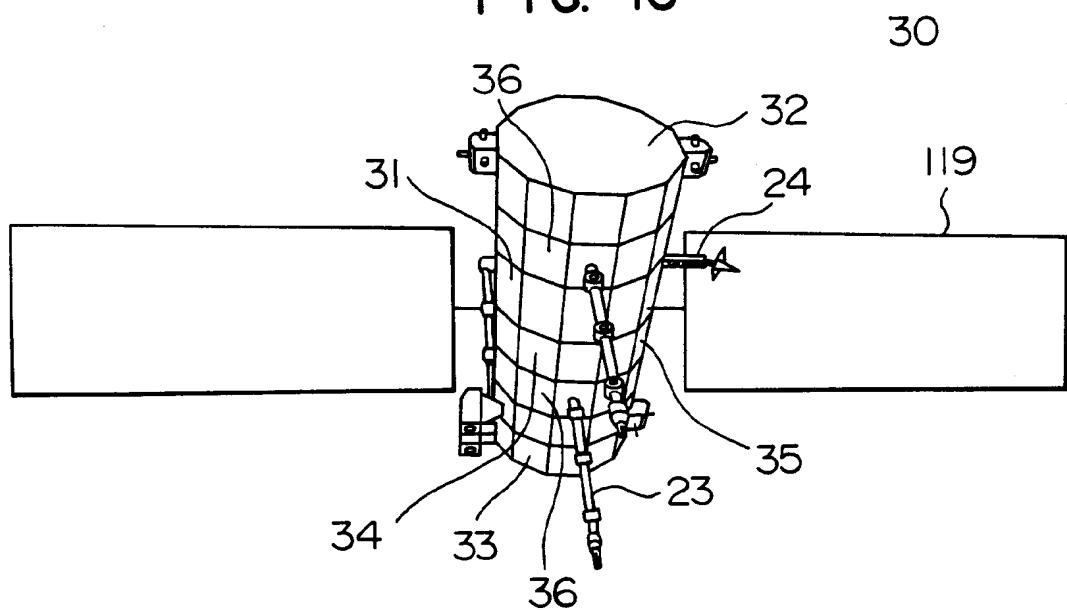


FIG. 18

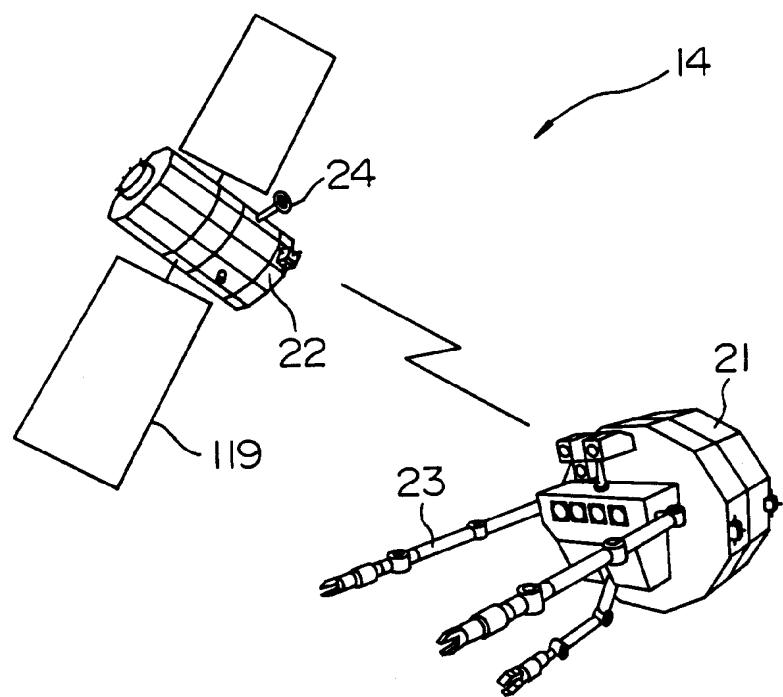


FIG. 17

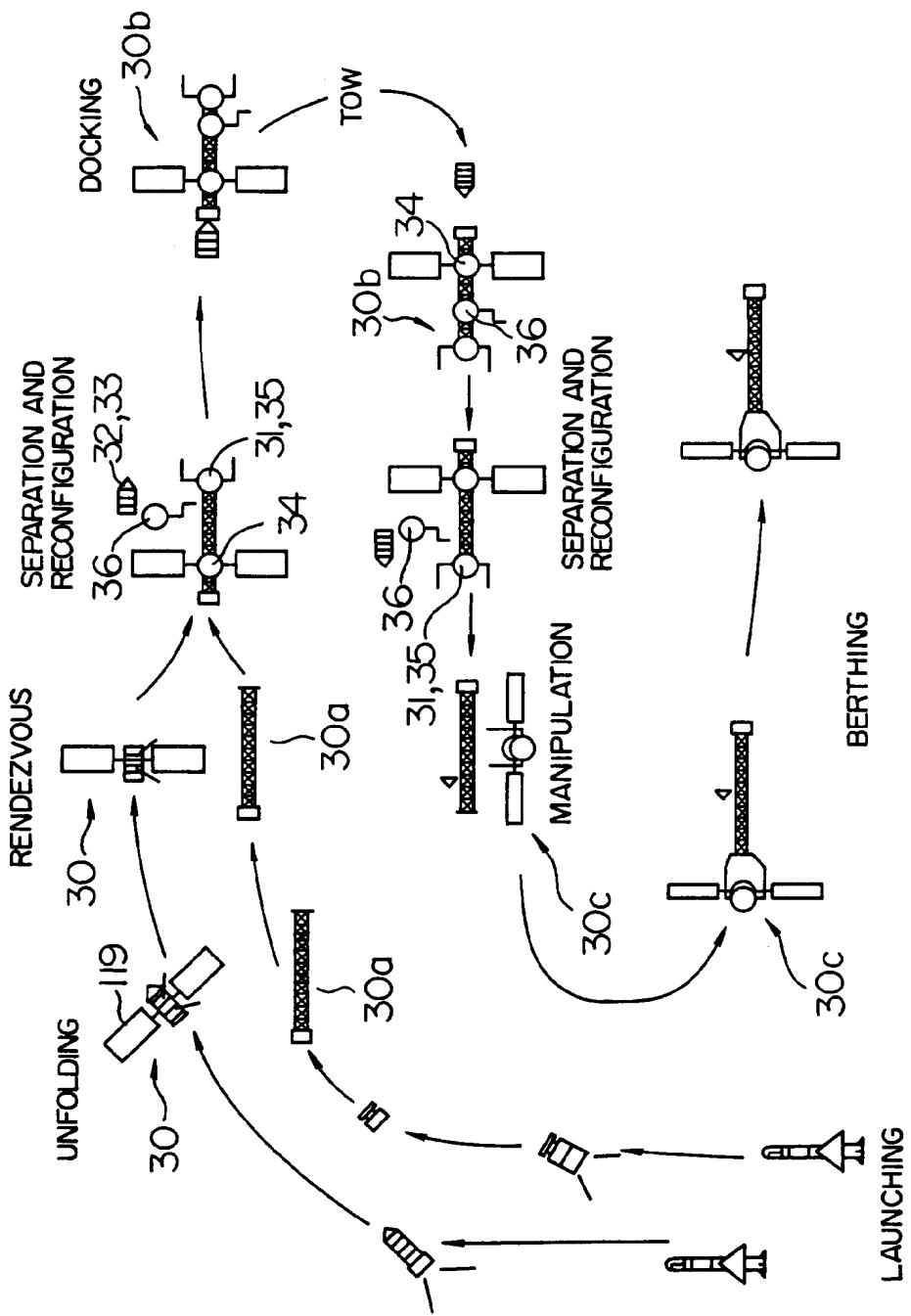


FIG. 19

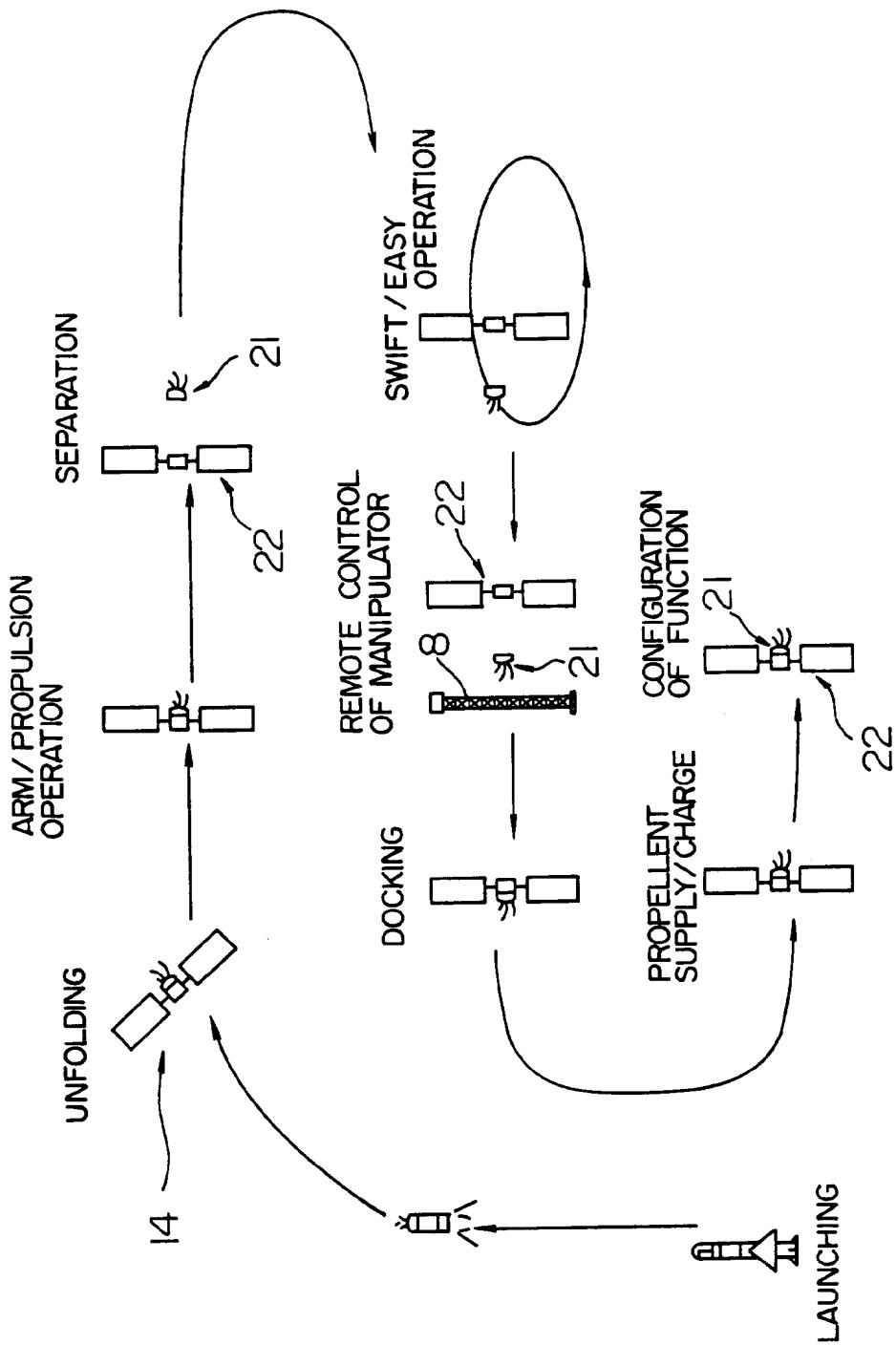


FIG. 20

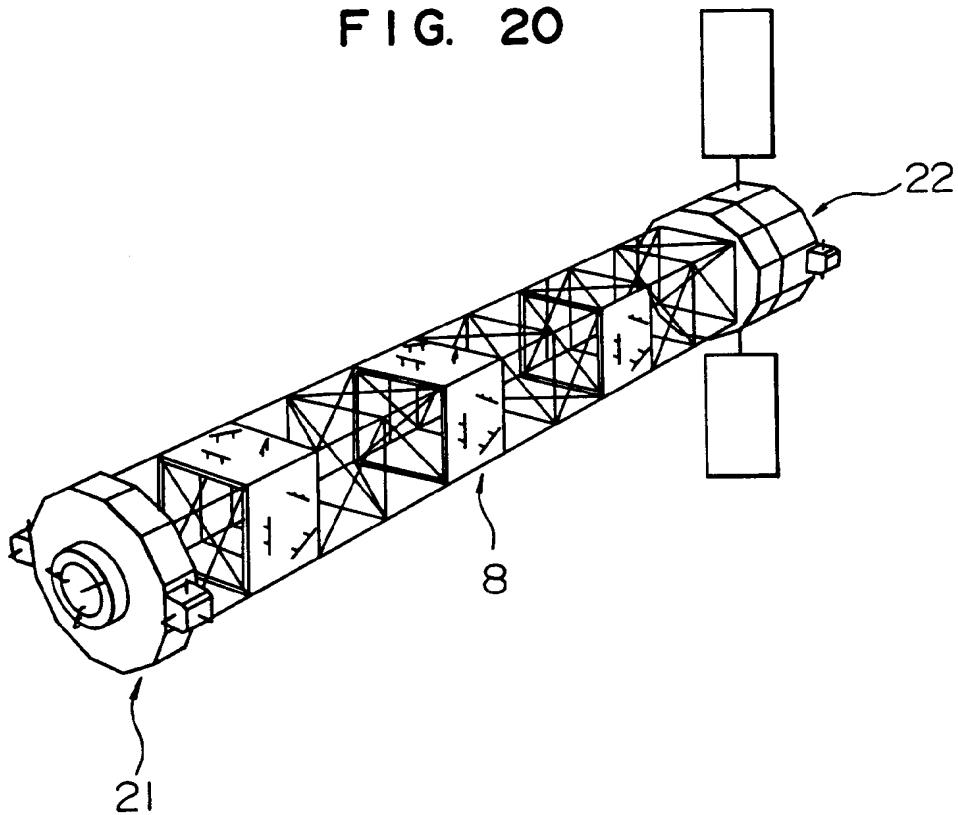


FIG. 21

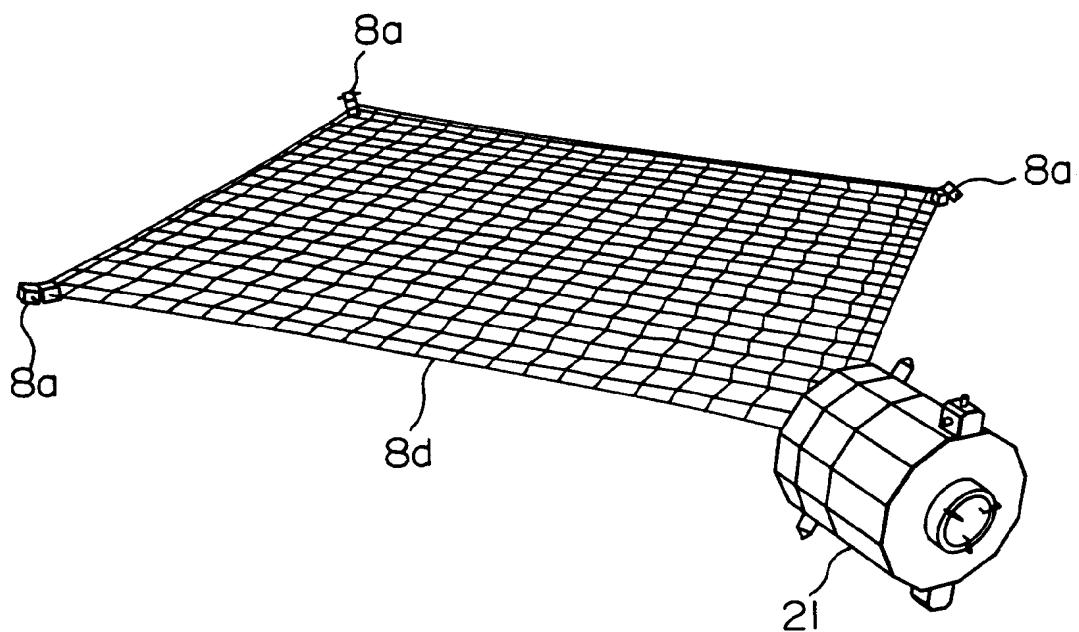


FIG. 22

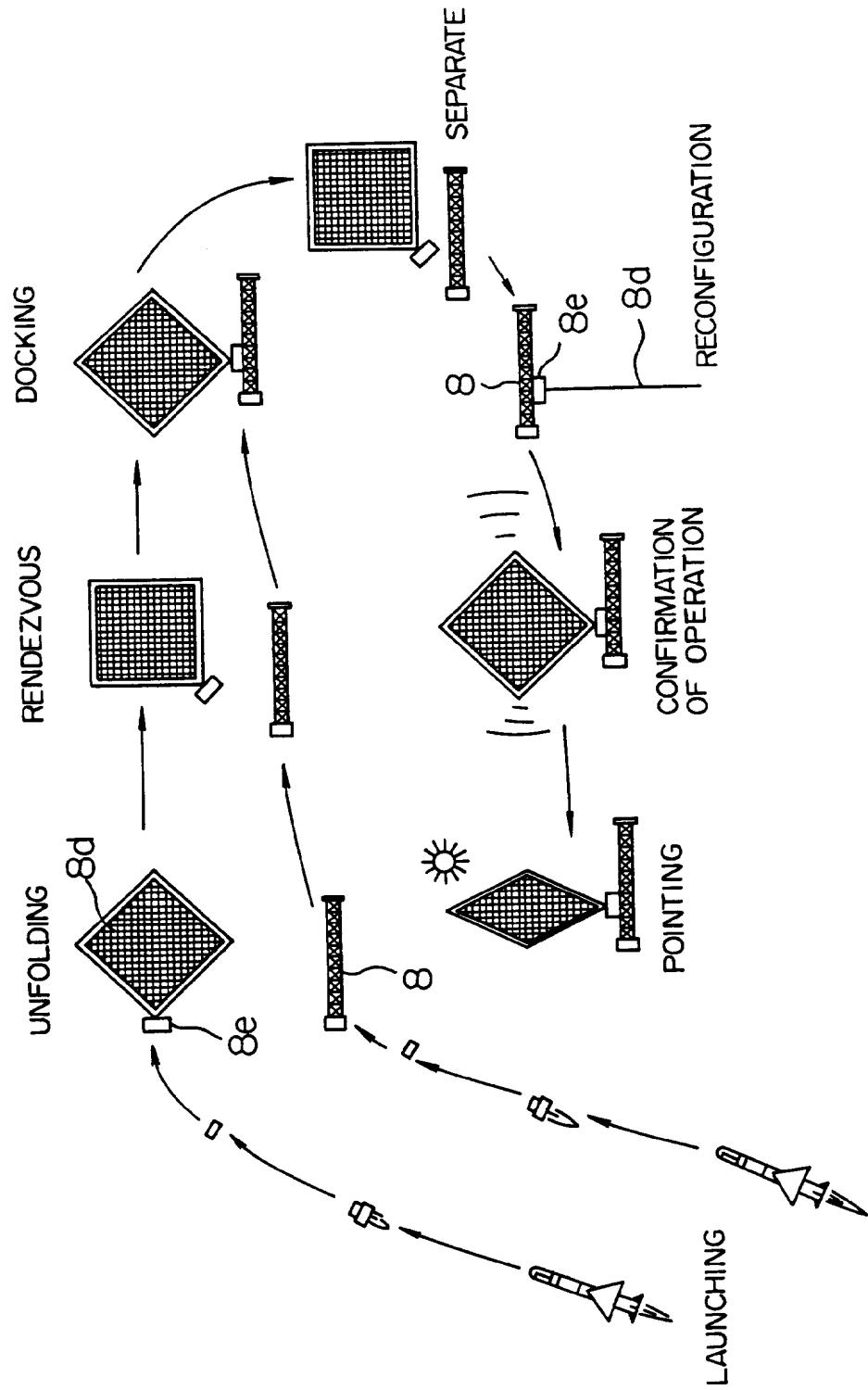


FIG. 23

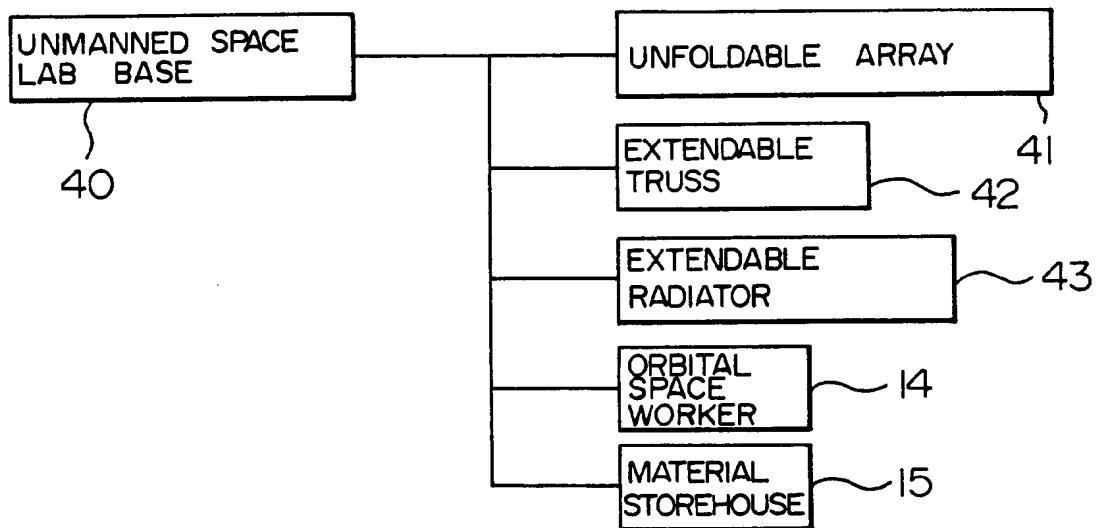


FIG. 24B

FIG. 24A

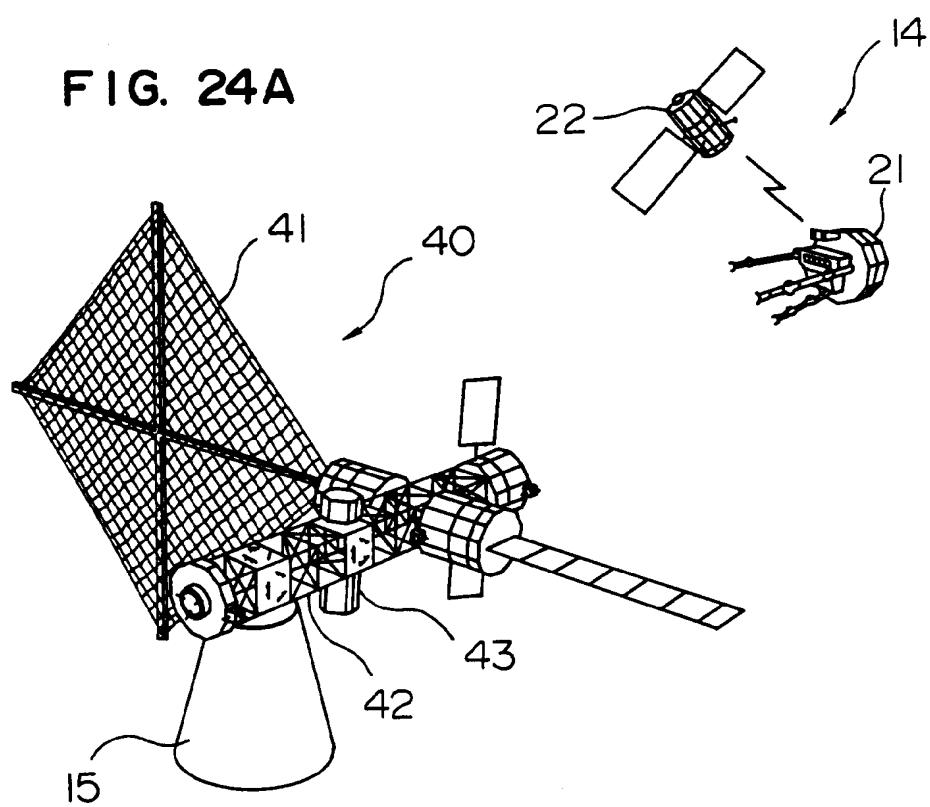


FIG. 25

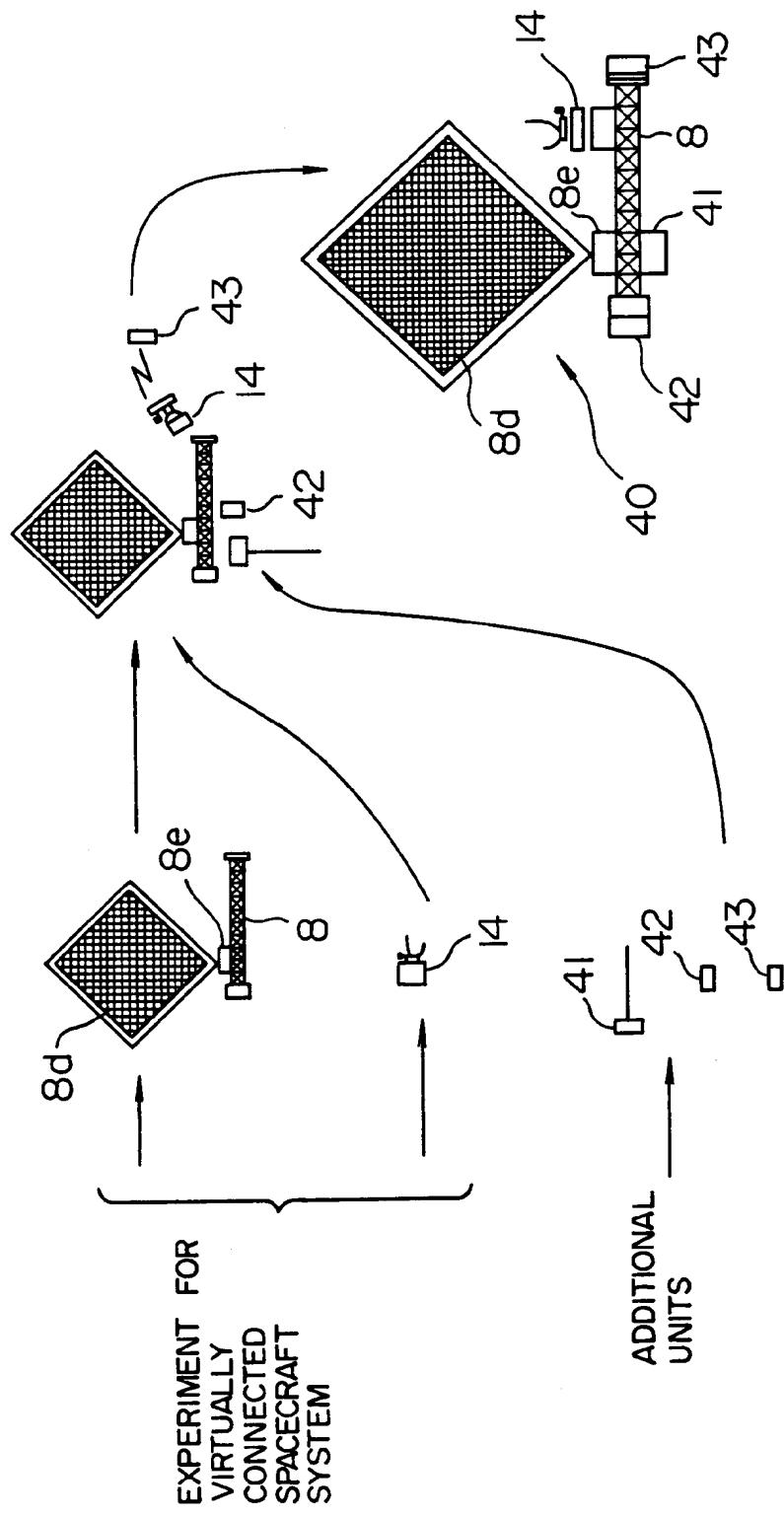


FIG. 26

